

### Deformable Displays for Continuous Eyes-Free Mobile Interaction

Simon Robinson

#### Céline Coutrix Jennifer Pearson

Juan Rosso Matheus Fernandes Torquato Laurence Nigay Matt Jones

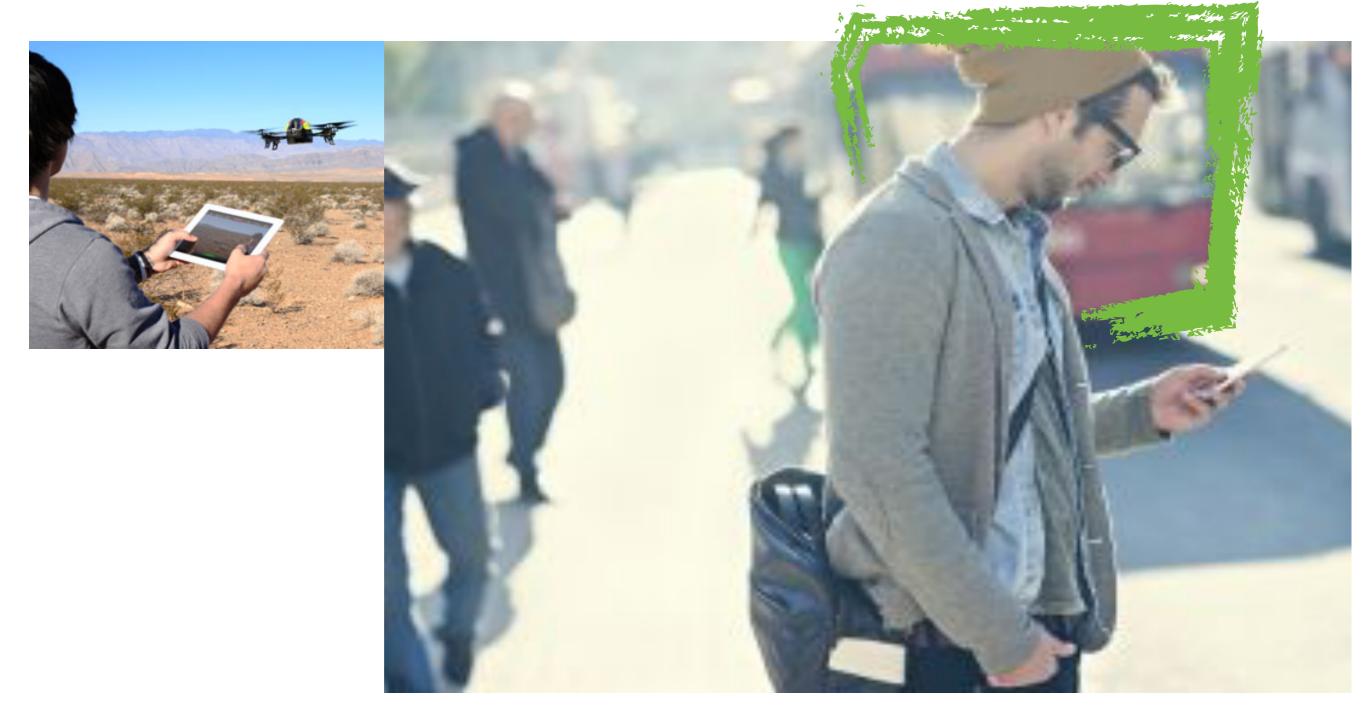














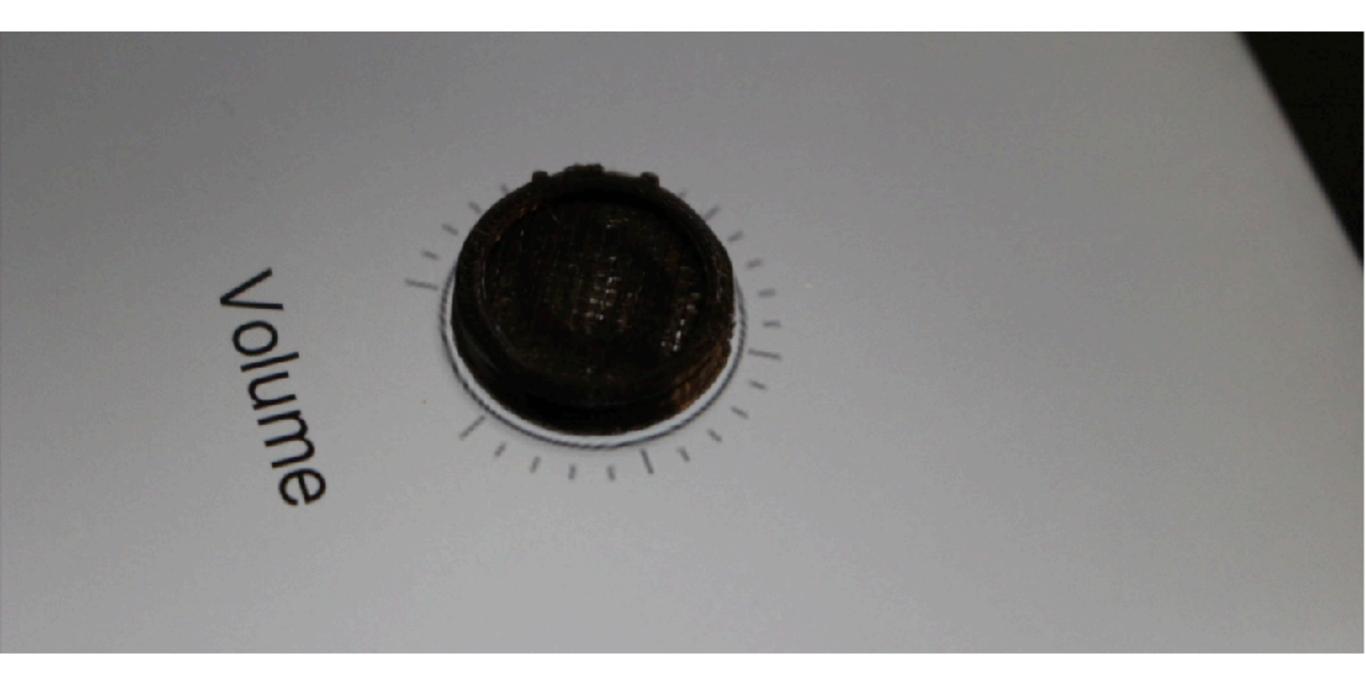


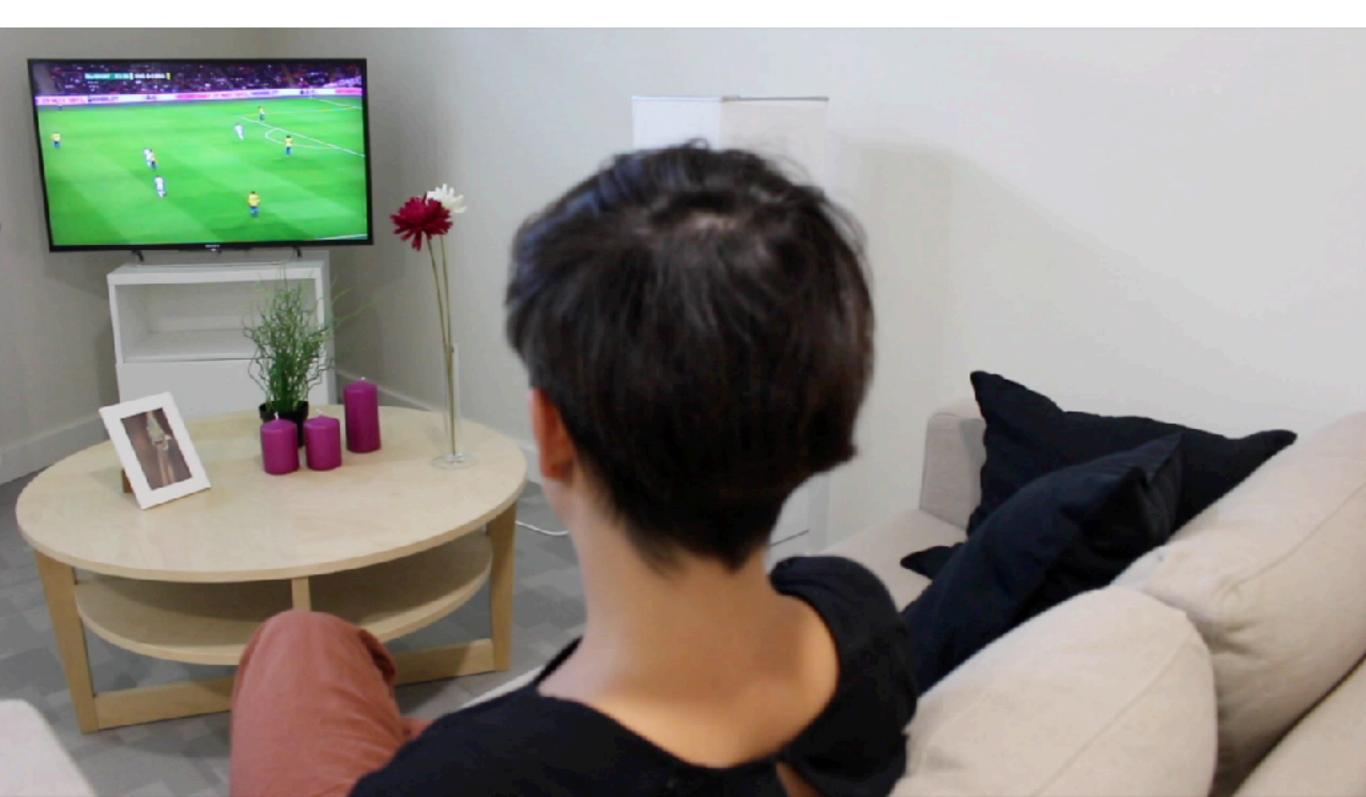


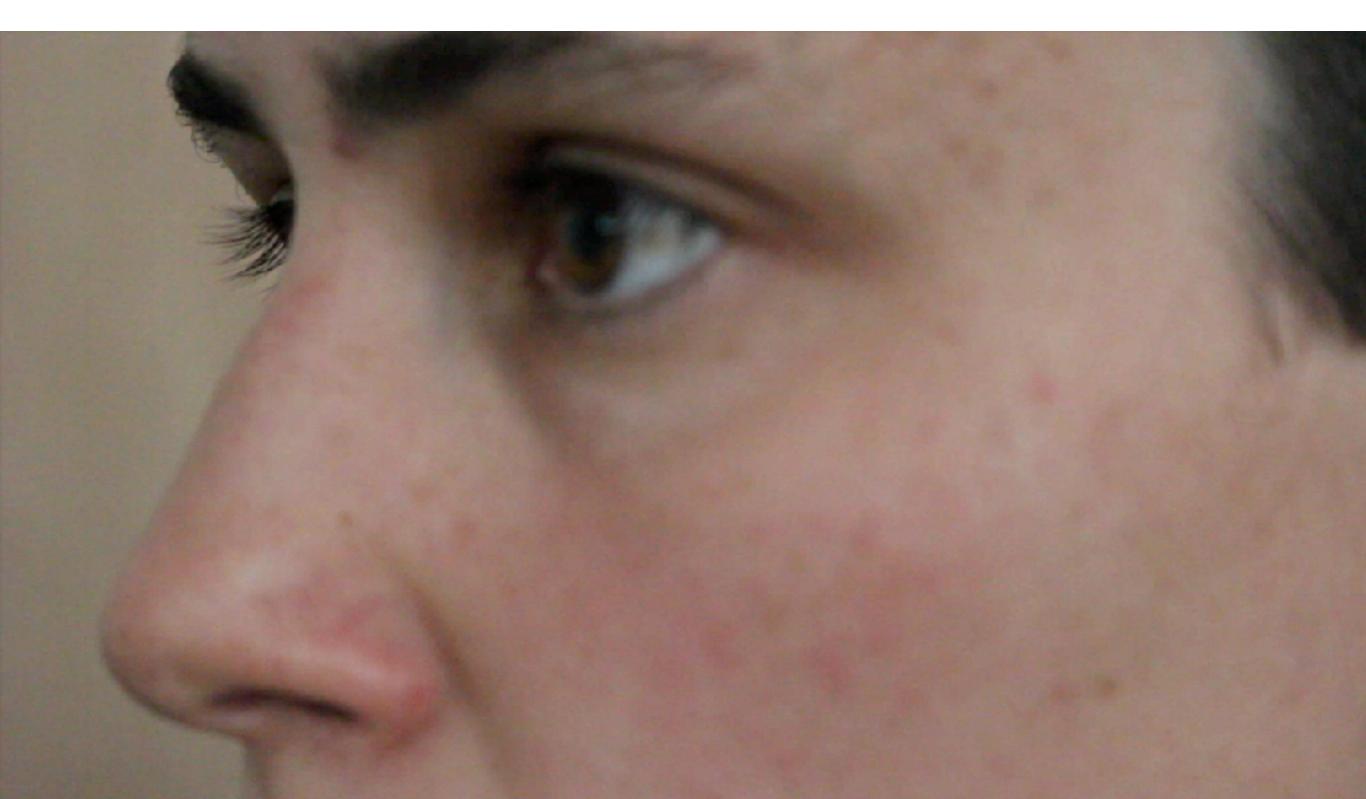
#### Low preference

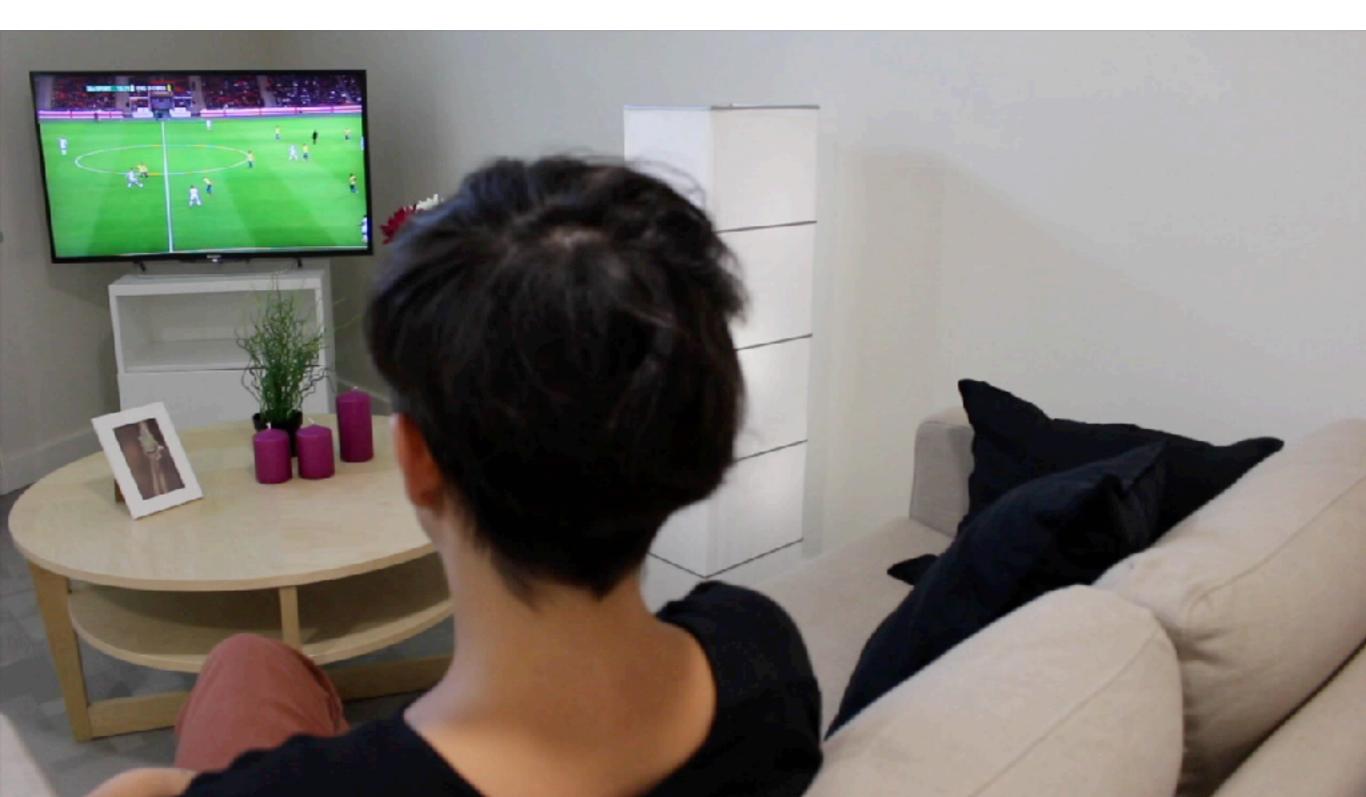
Low performance

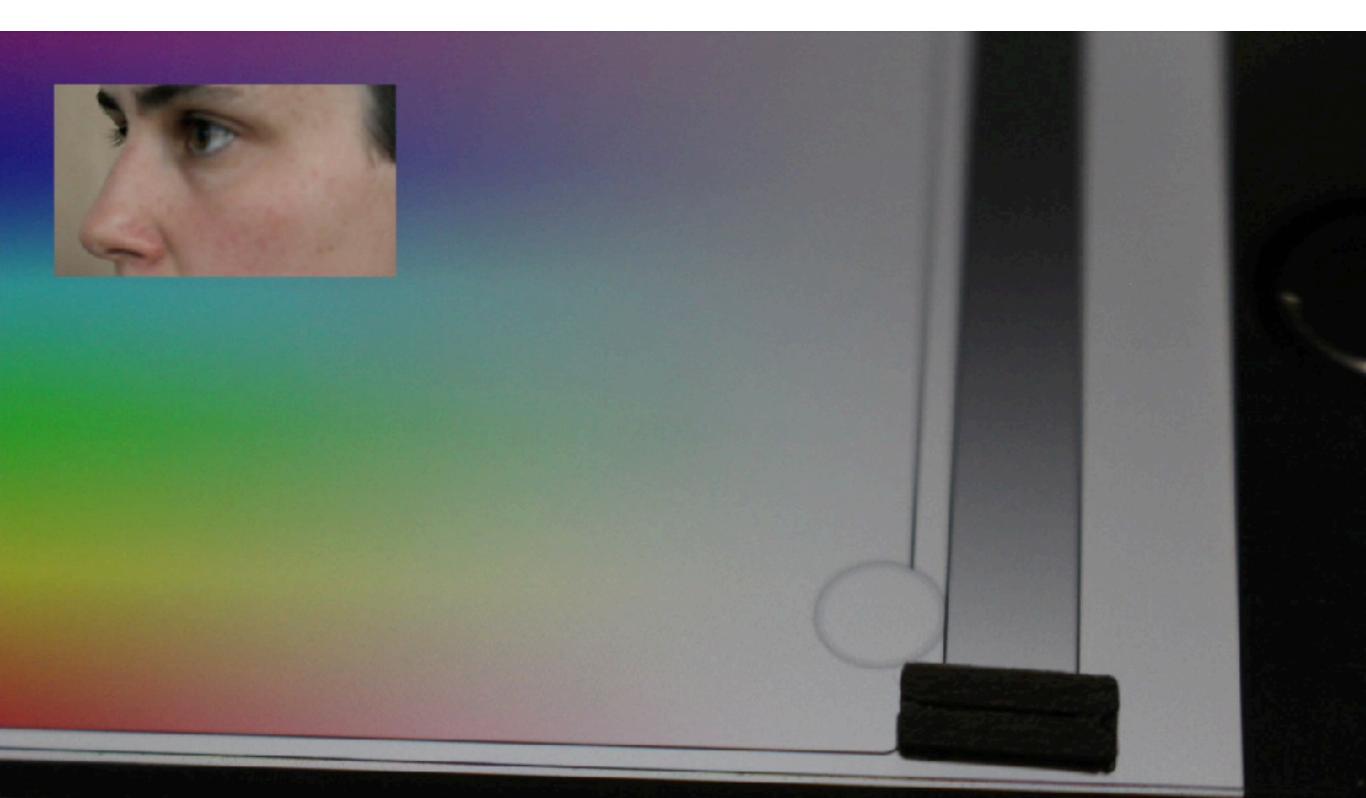
Low safety

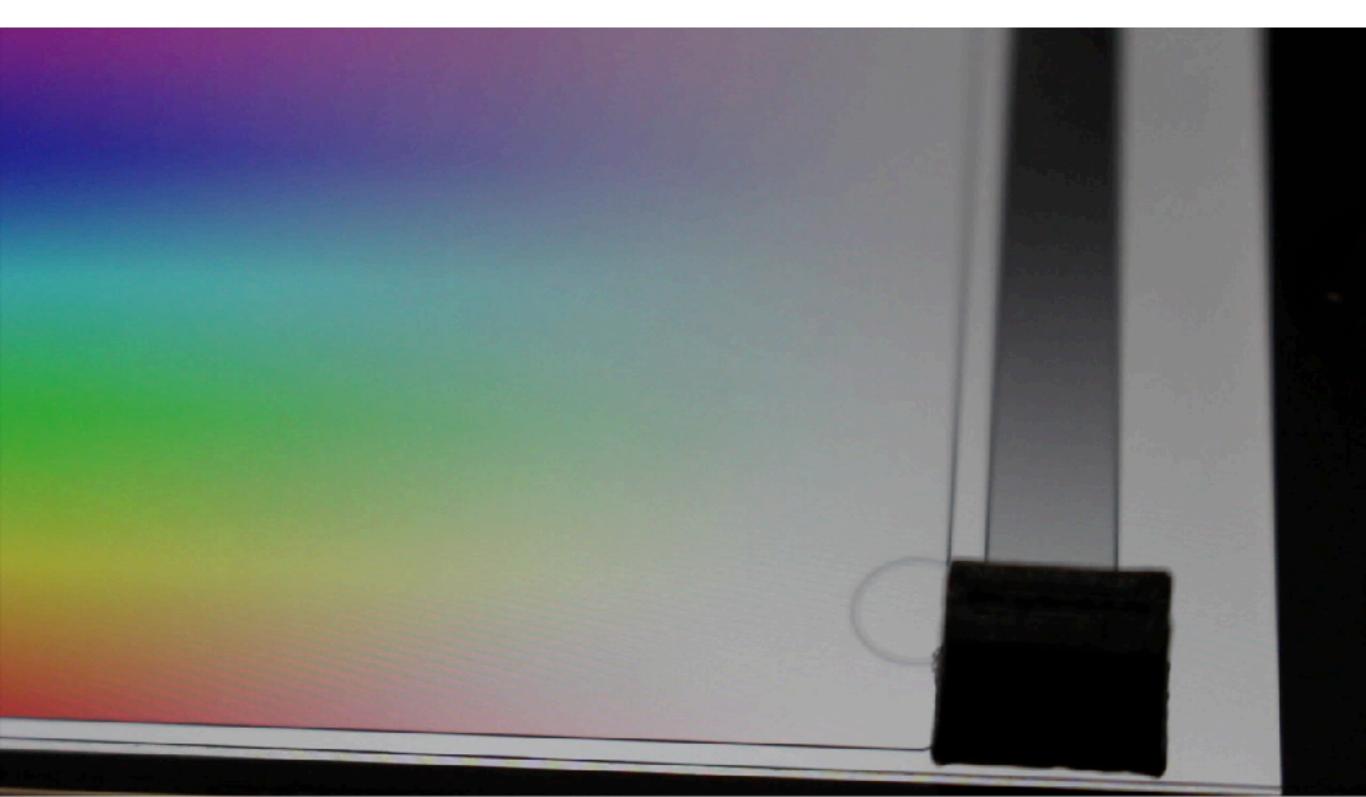


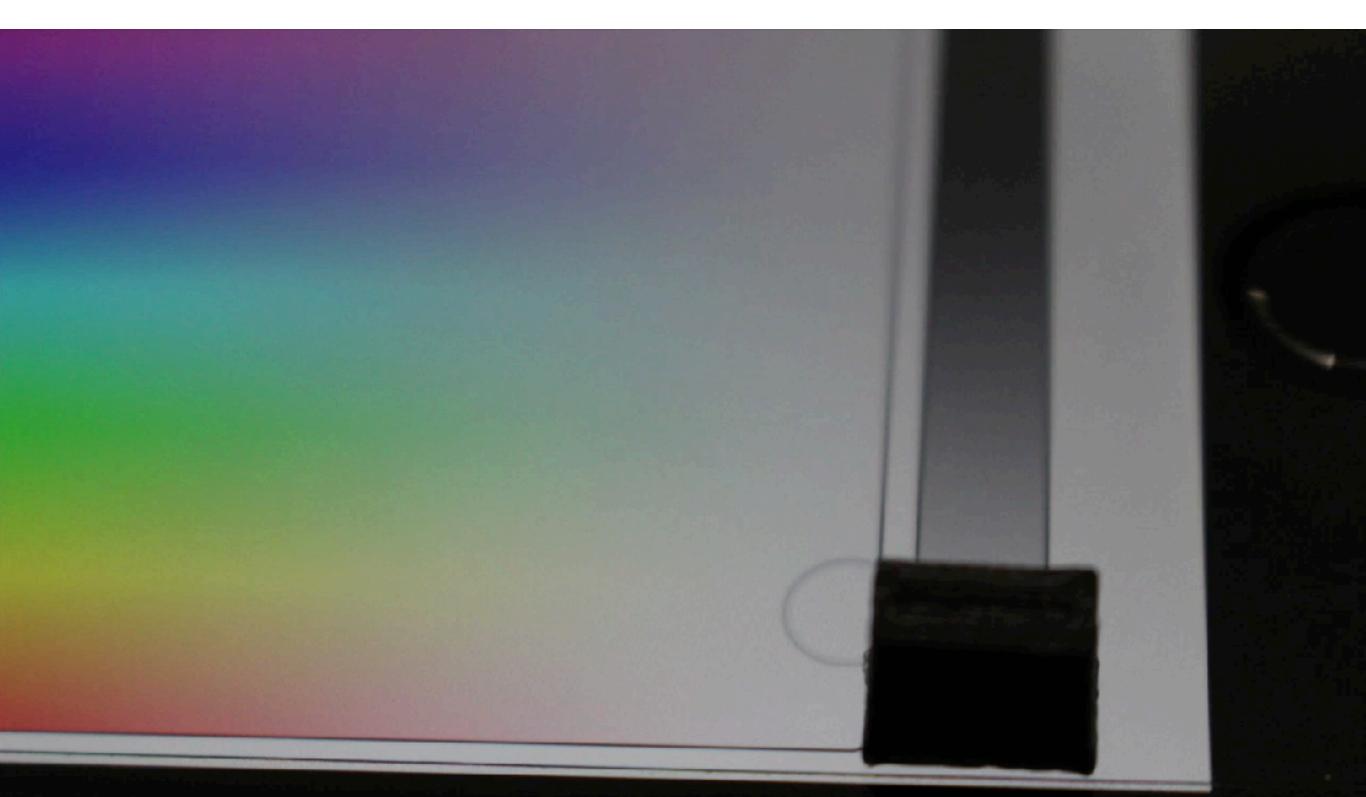








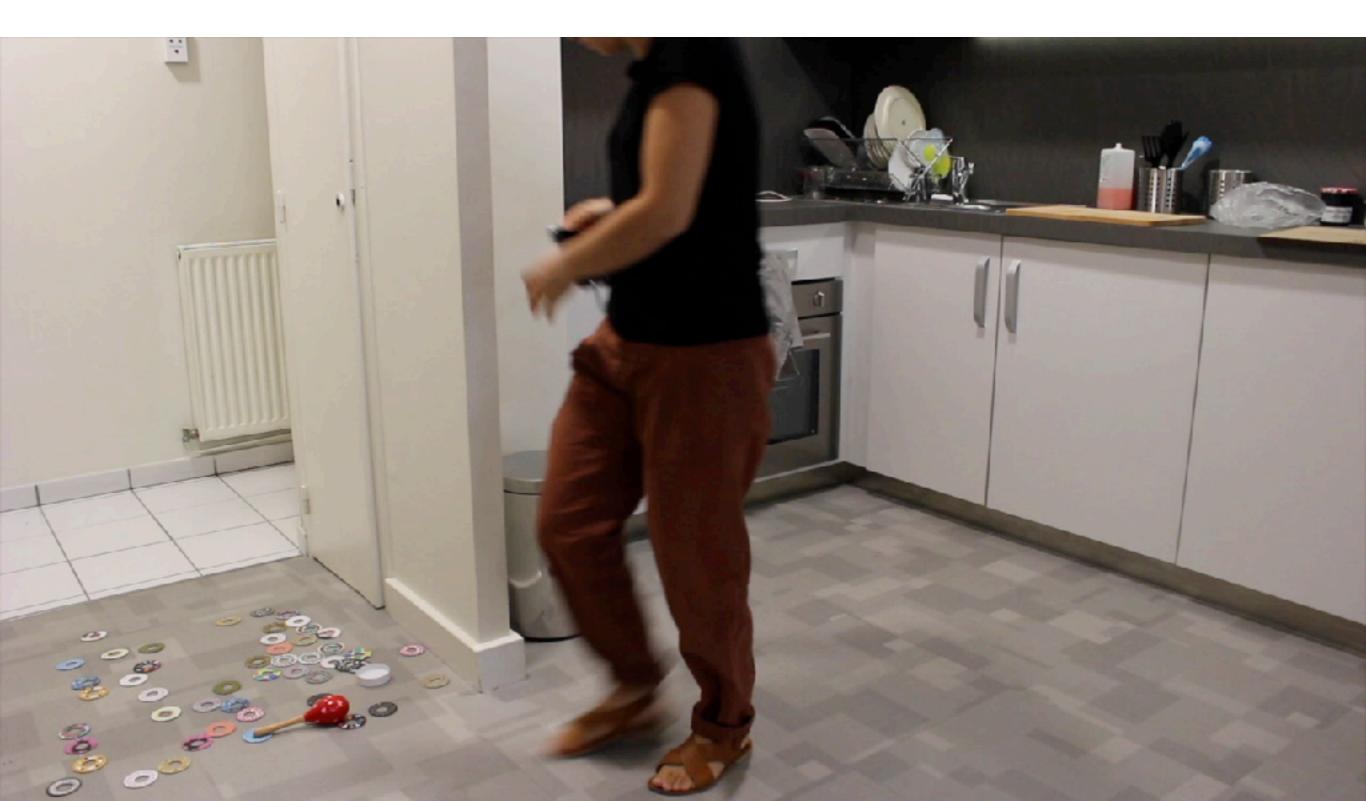


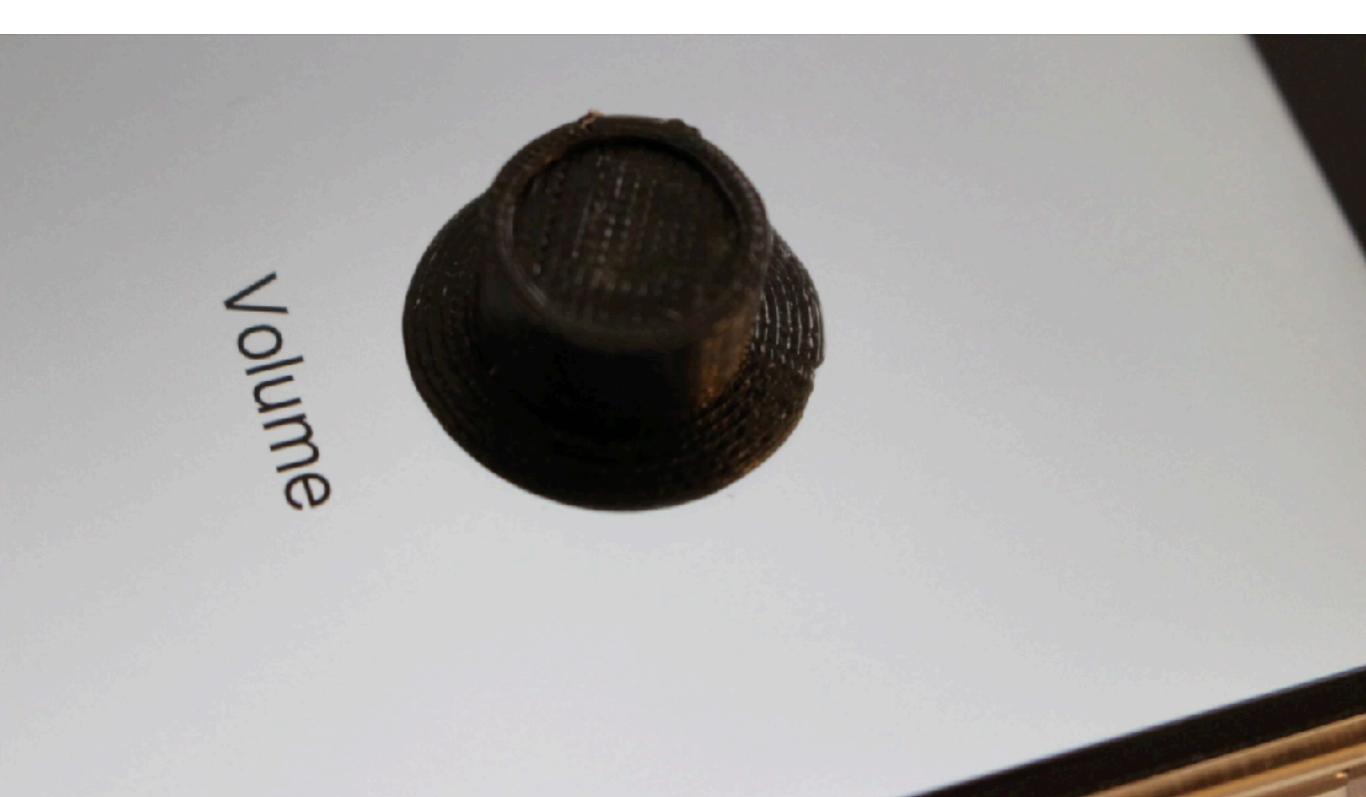


### During half-time and advertisements

### she washes the dishes







# Benefits of Emergeables vs. new interaction



#### Karrer *et al.*, 2011

Serrano et al., 2014

Ramakers et al., 2014

### ≠ known tangible control

# Benefits of Emergeables vs. additional controls



Florian Born, 2013

Jansen et al. 2012

#### ≠ no additional articulatory task

## Benefits of Emergeables vs. discrete control



Harrison and Hudson, 2009

http://tactustechnology.com

#### ≠ continuous control

# Benefits of Emergeables for eyes-free mobile tasks

+ known tangible controls

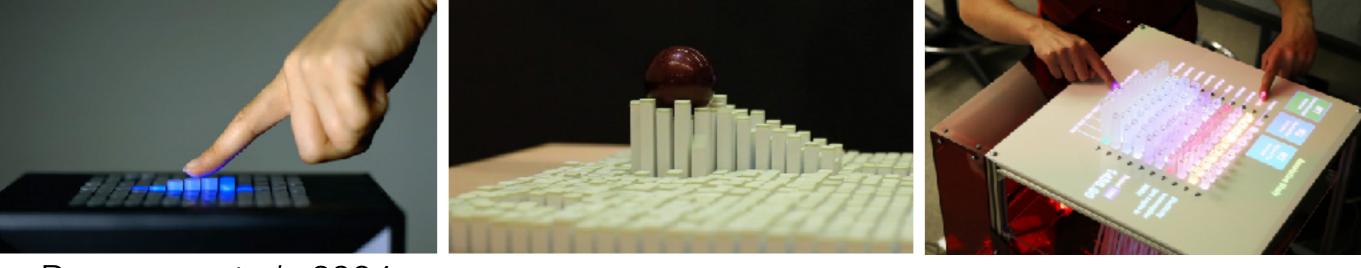
+ no additional articulatory task

+ continuous control

## Difficulty: technology



### Technology: current approach



Poupyrev et al., 2004

Follmer et al., 2013

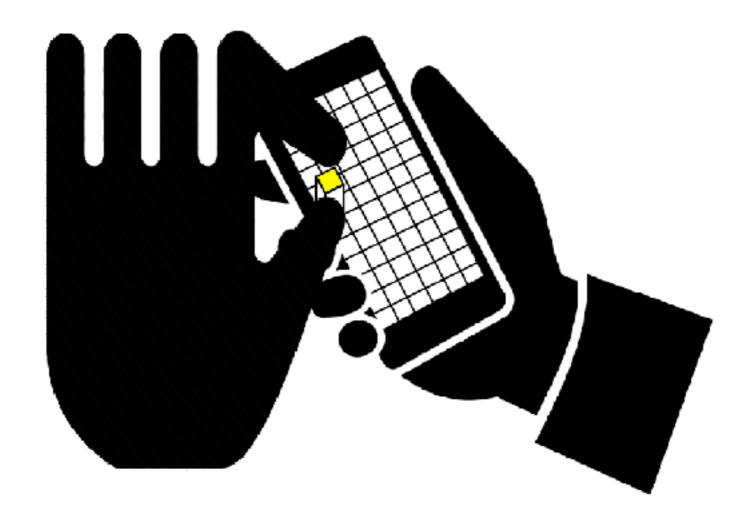
Taher *et al.*, 2015



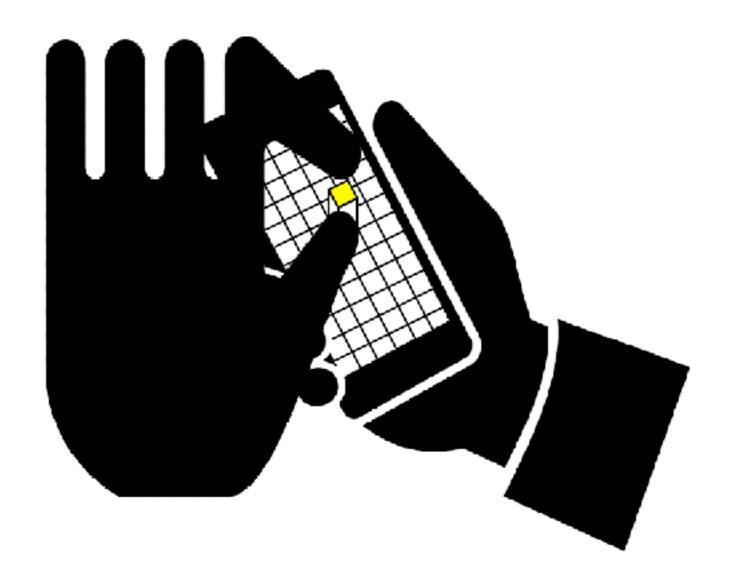




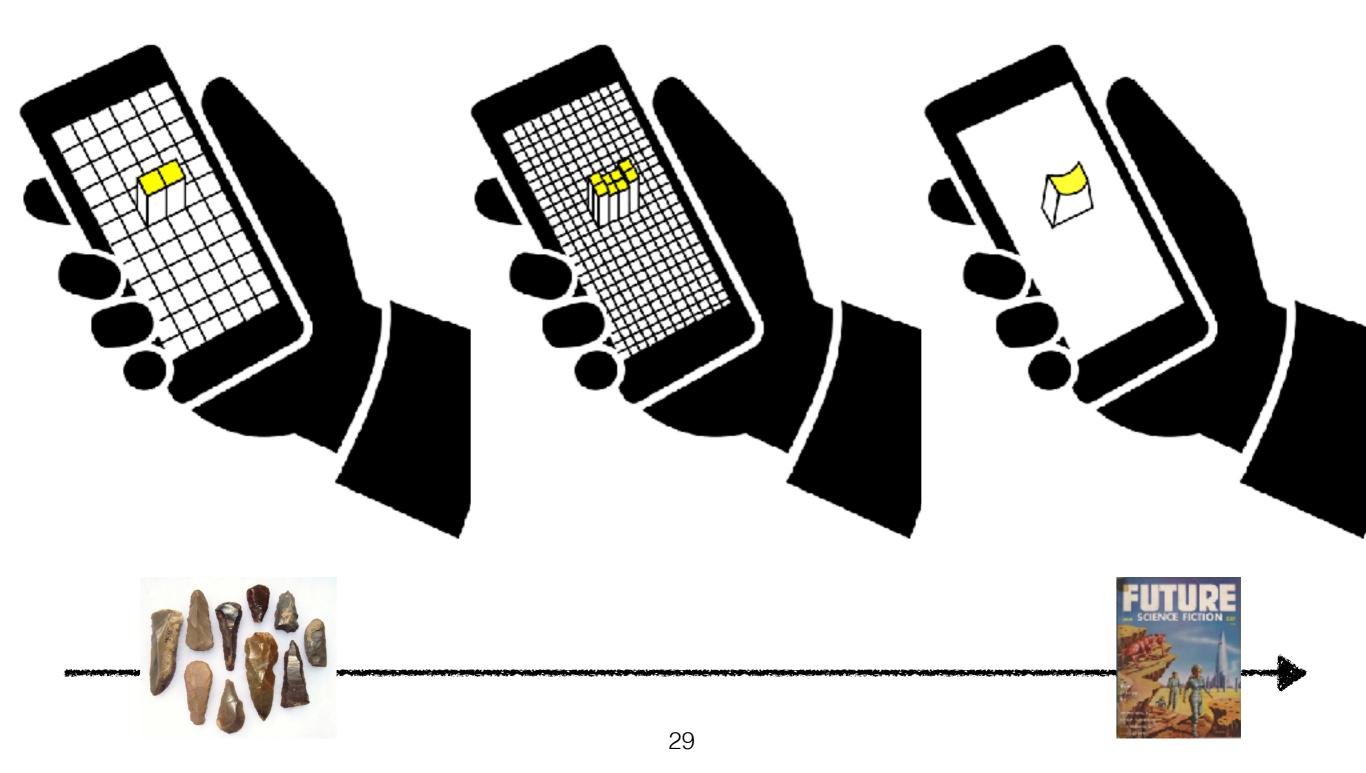
### Manipulation: Translation



### Manipulation: Rotation



### Resolution



### Is it worth the effort? How far are we today?



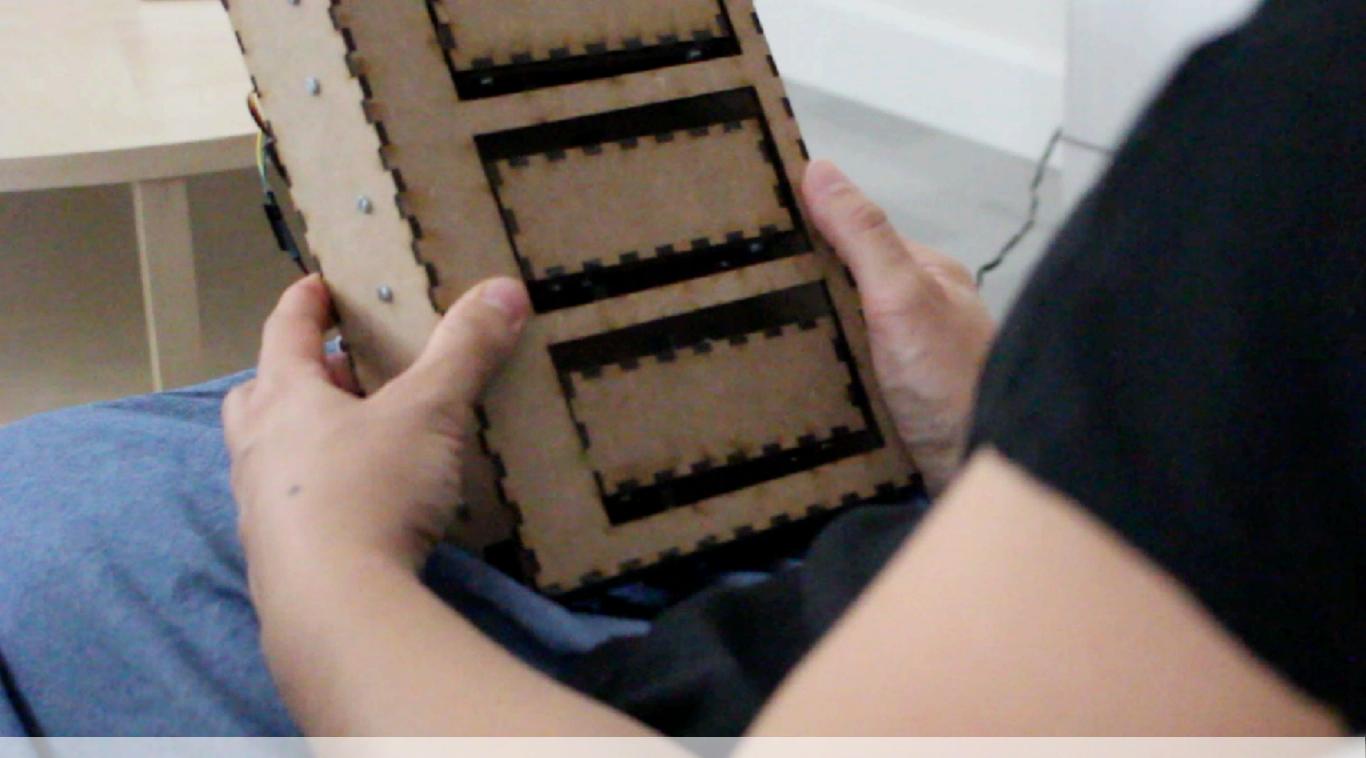




## Prototype simulating high-resolution: tailored for experiment

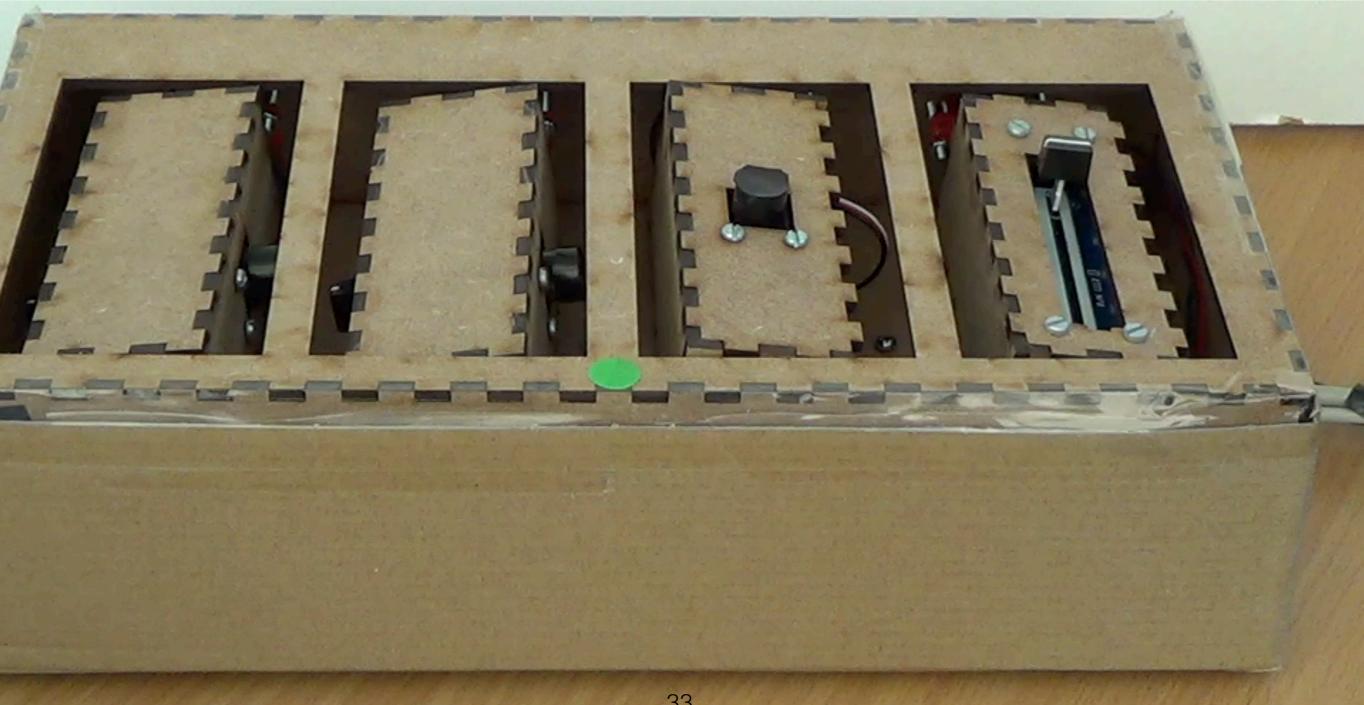






High-resolution: Simulation<sub>32</sub> prototype

## High-resolution: Simulation prototype



### Is it worth the effort?





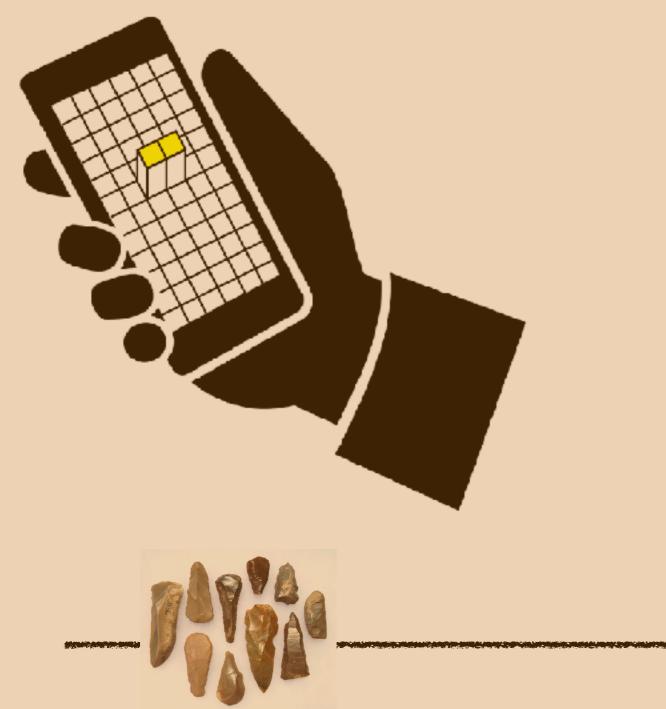
### Is it worth the effort? How far are we today?





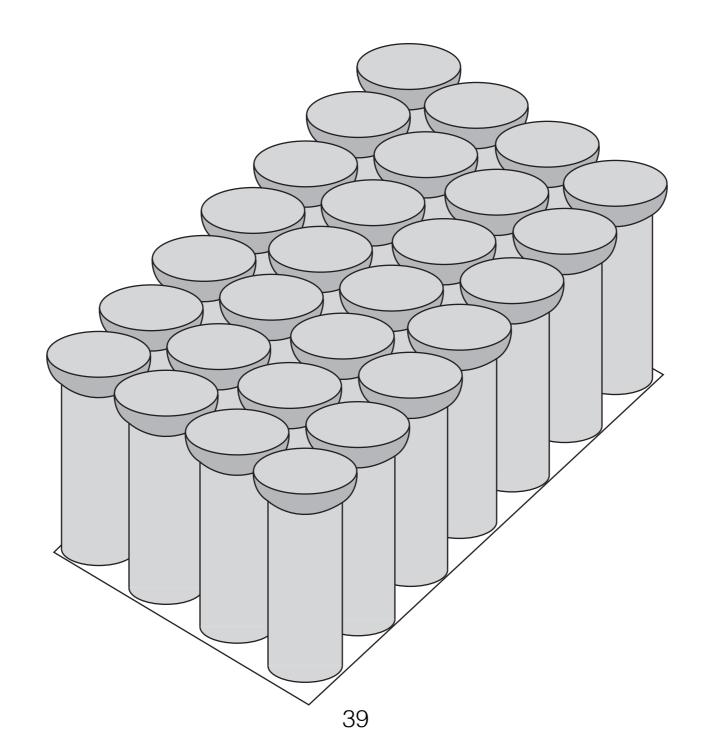


### How far are we today?

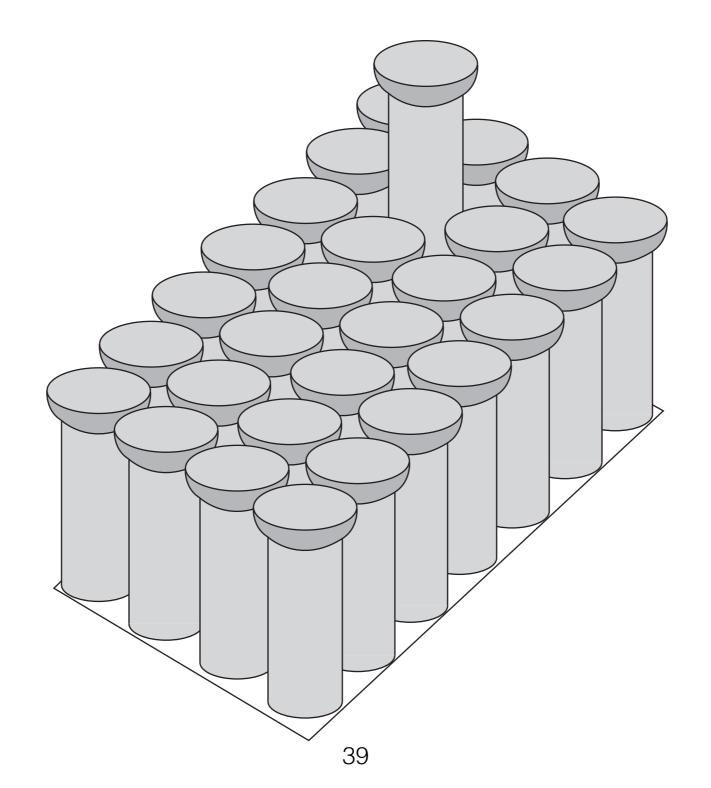


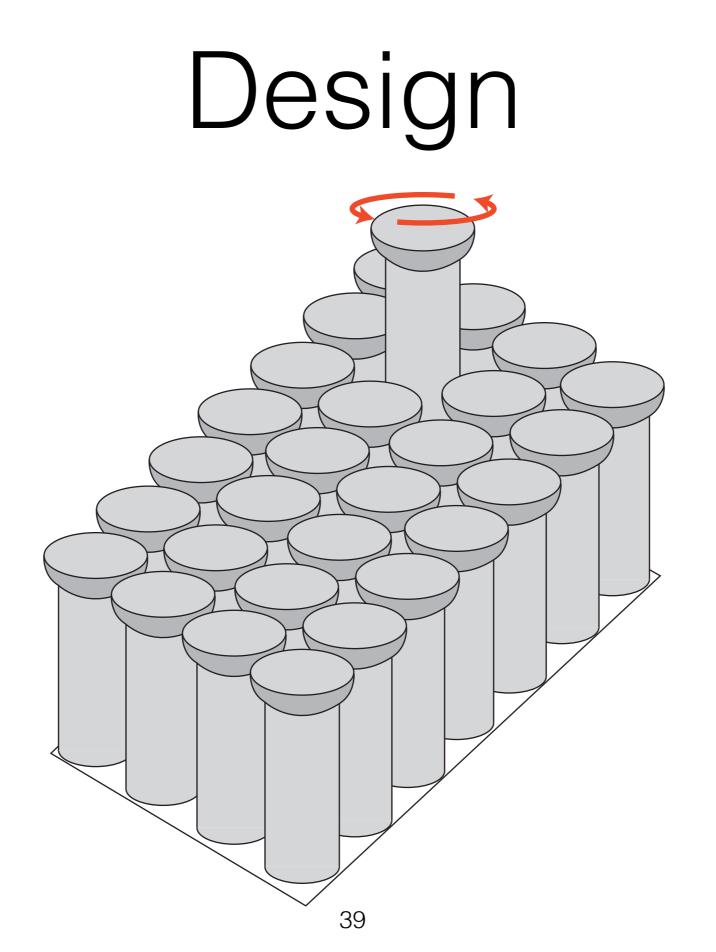
# Low-resolution prototype

# Design

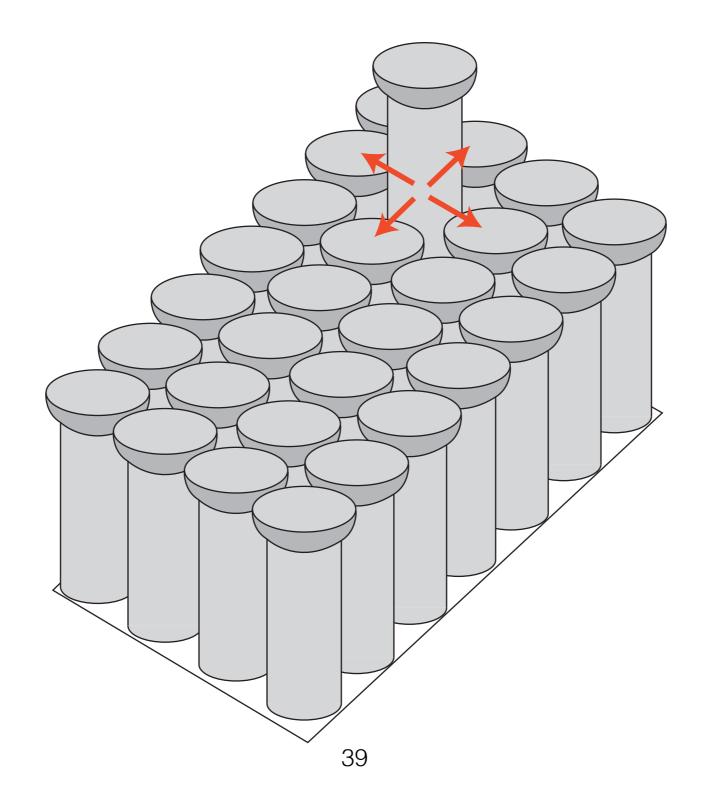










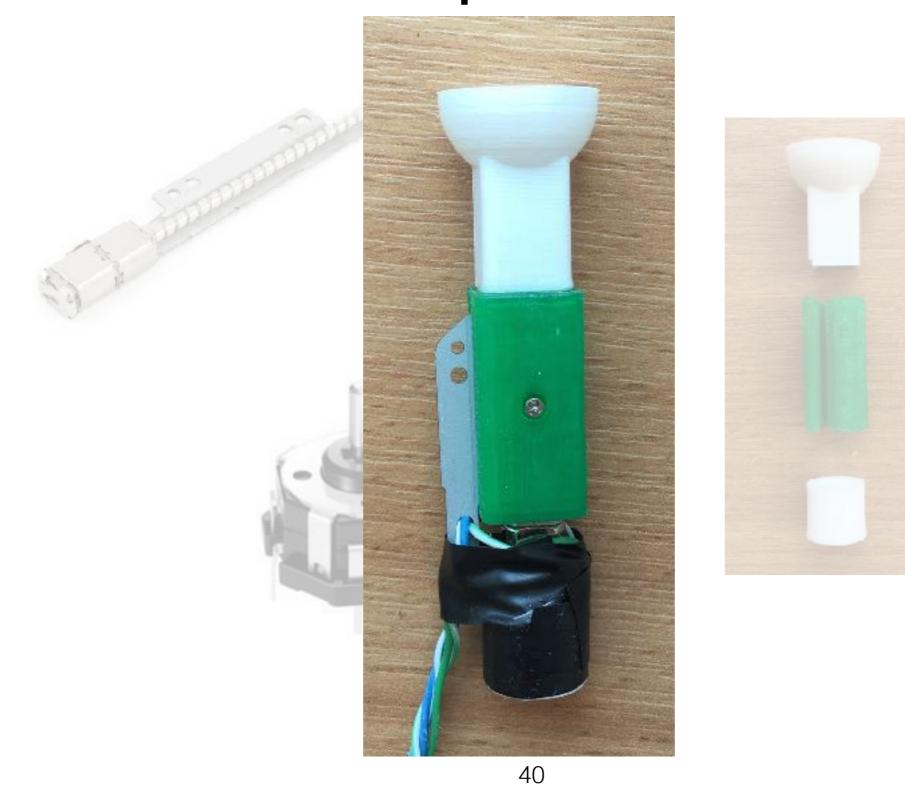


### Components

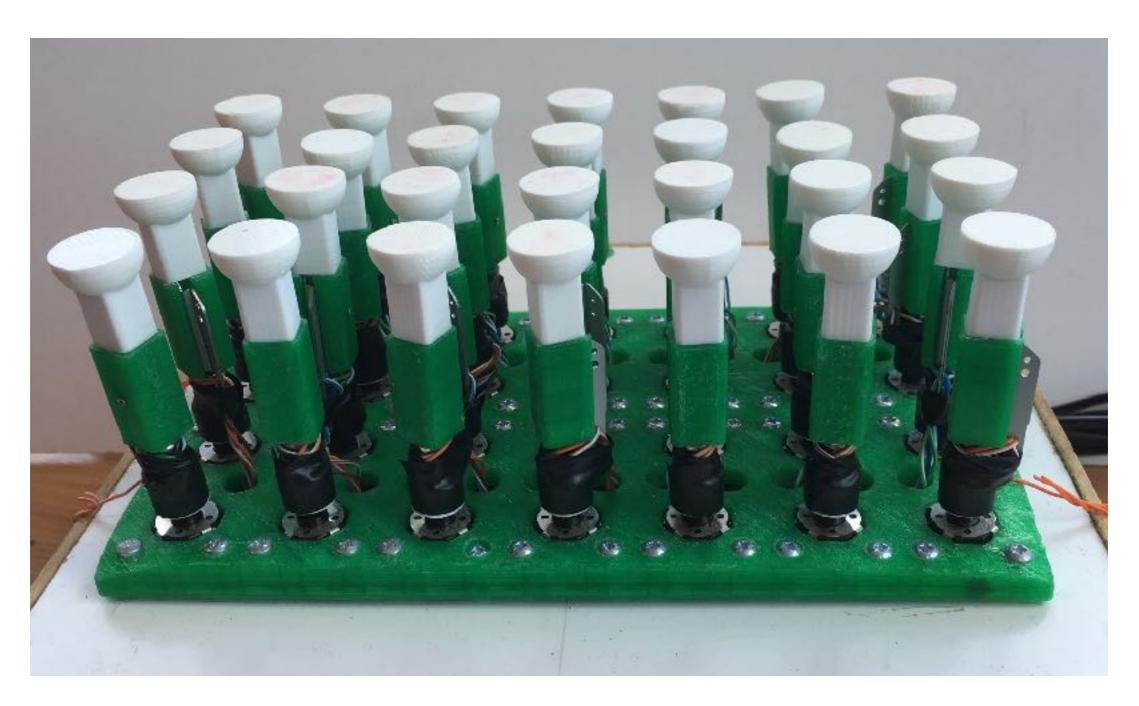




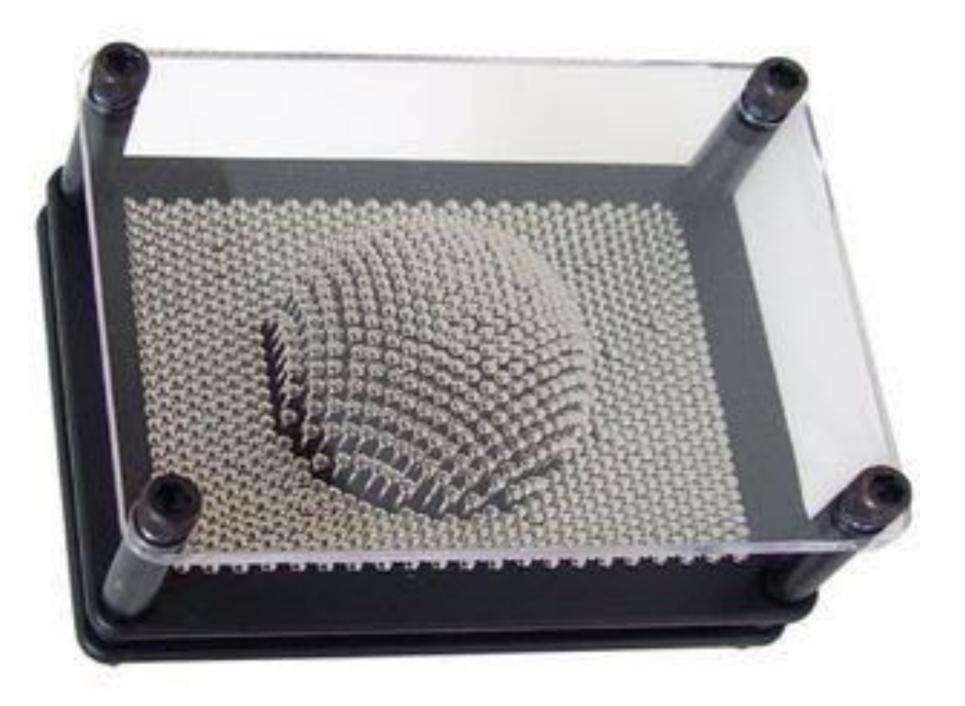
# Components



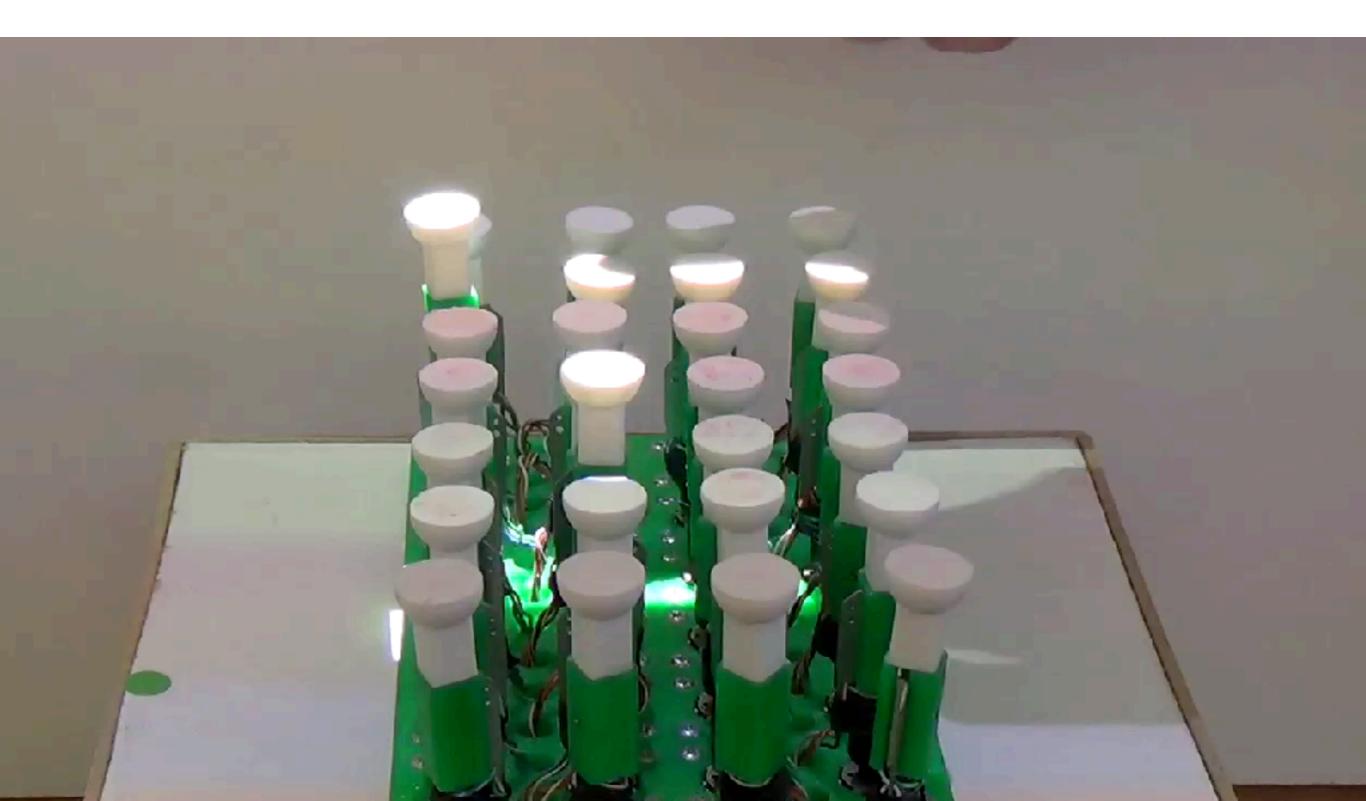
# Prototype



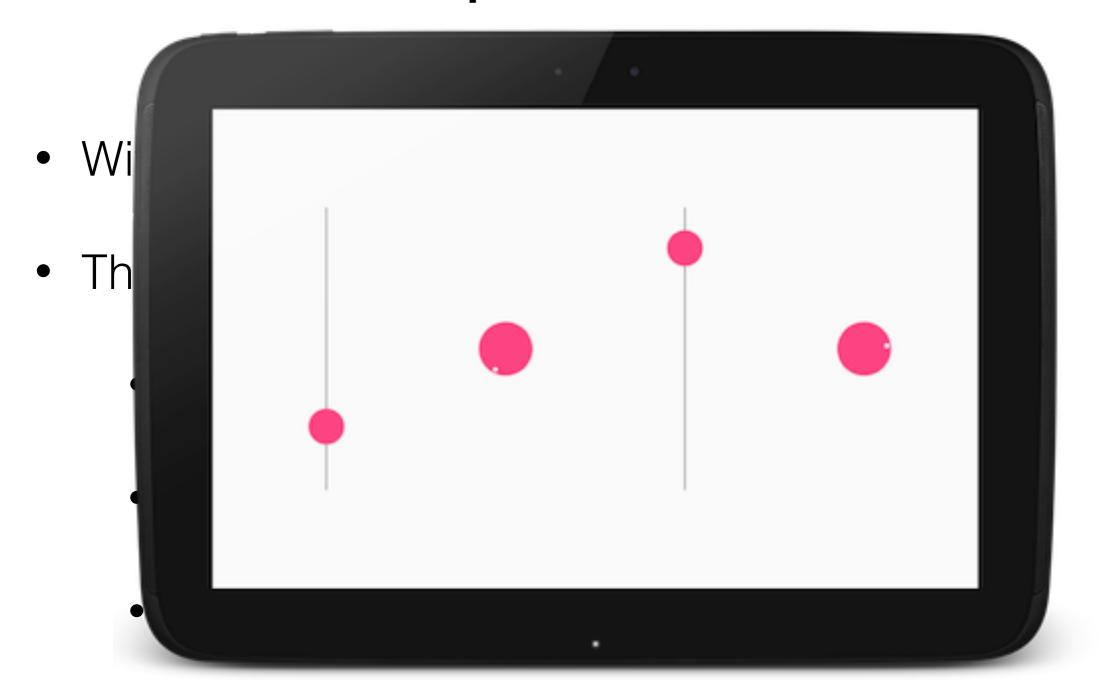
# Prototype



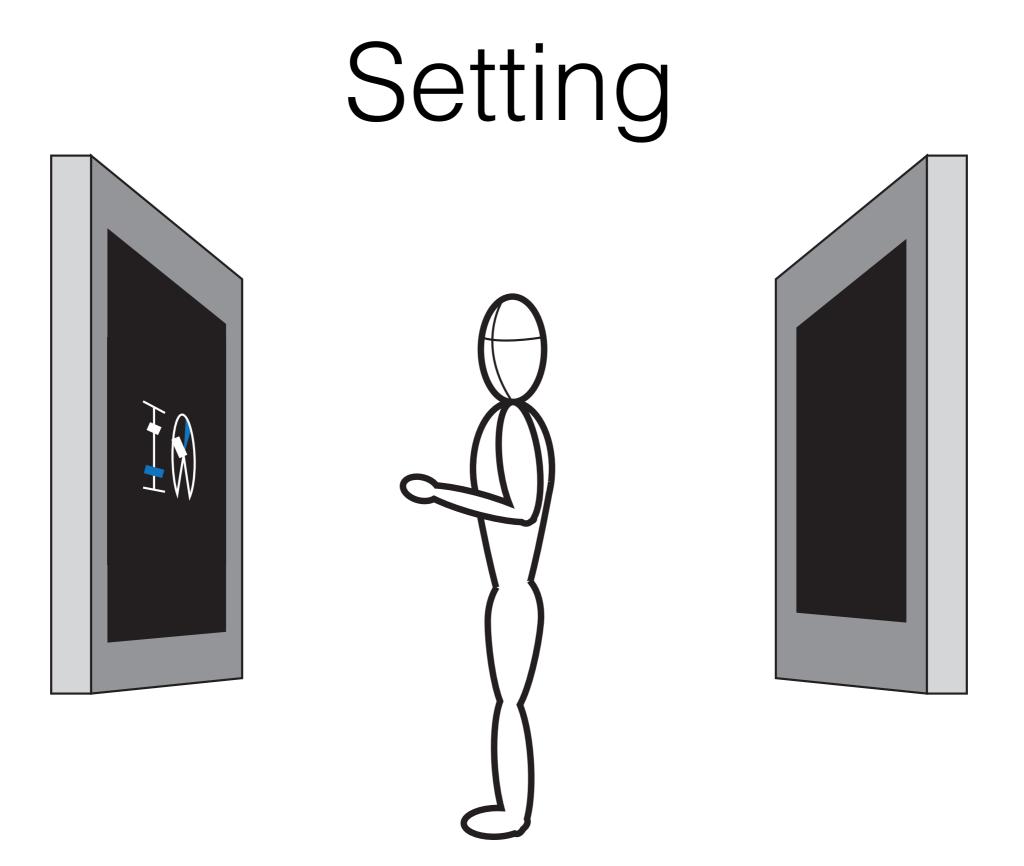
#### Controls



- Within-subjects design
- Three interfaces:
  - High-resolution prototype
  - Low-resolution prototype
  - Graphical comparison interface

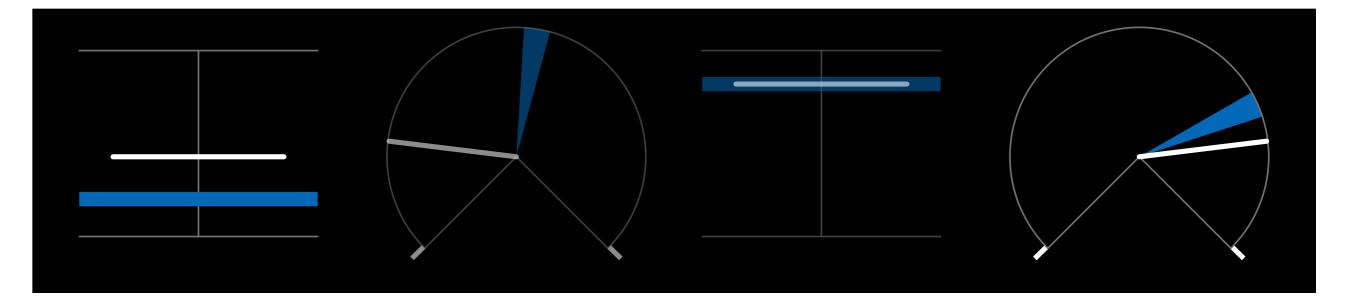


- Three independent variables
  - Resolution: GUI, low-resolution, highresolution
  - Complexity: 1 or 2 widgets (controlled simultaneously)
  - Widget: dial or slider

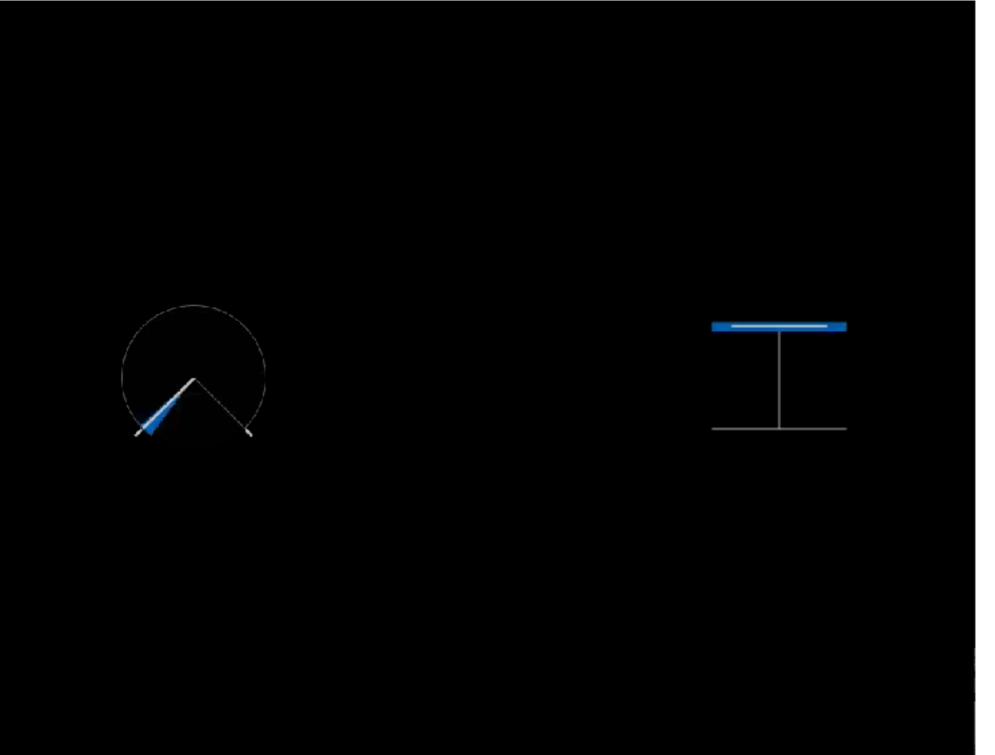


# Pursuit Tasks

- Solid white line: user's controller
- Blue shaded areas: target region



#### Pursuit Tasks



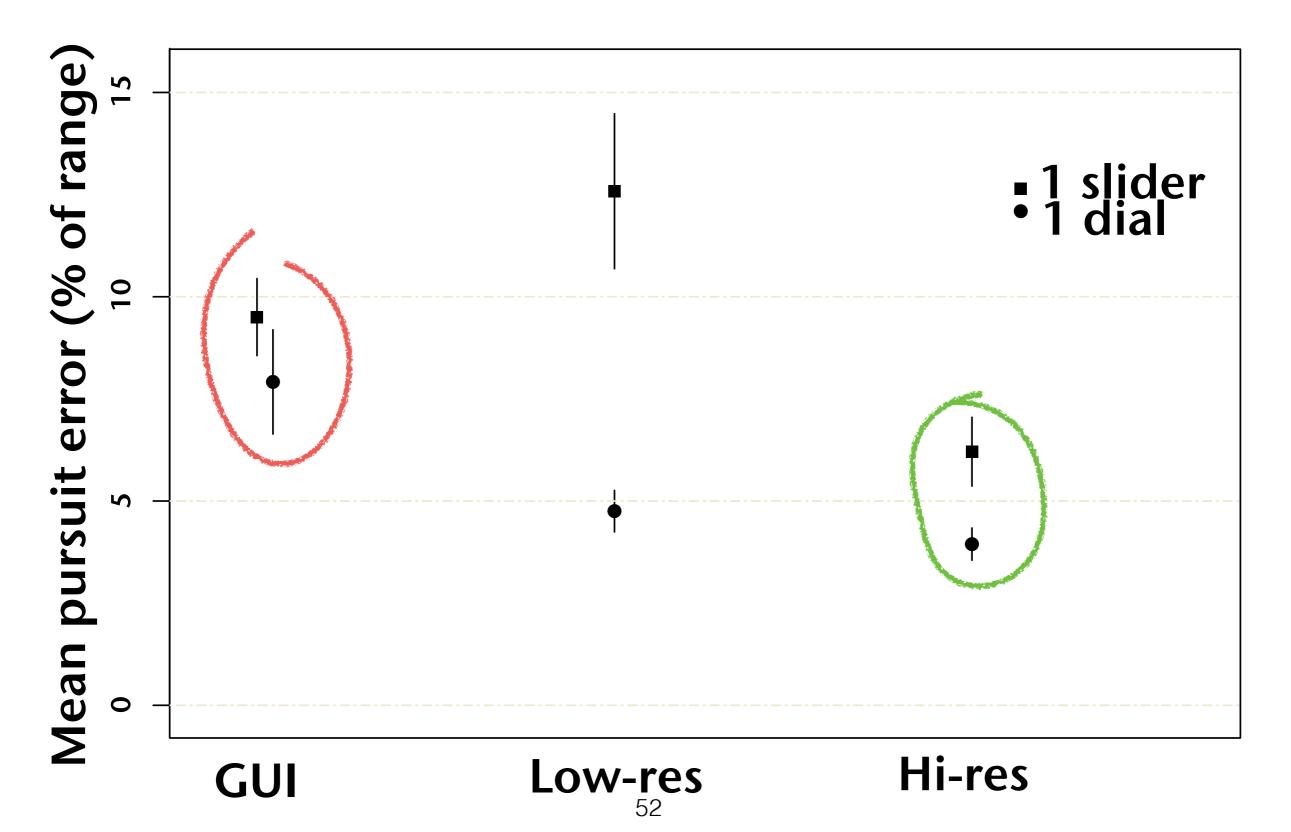
# Experimental Design

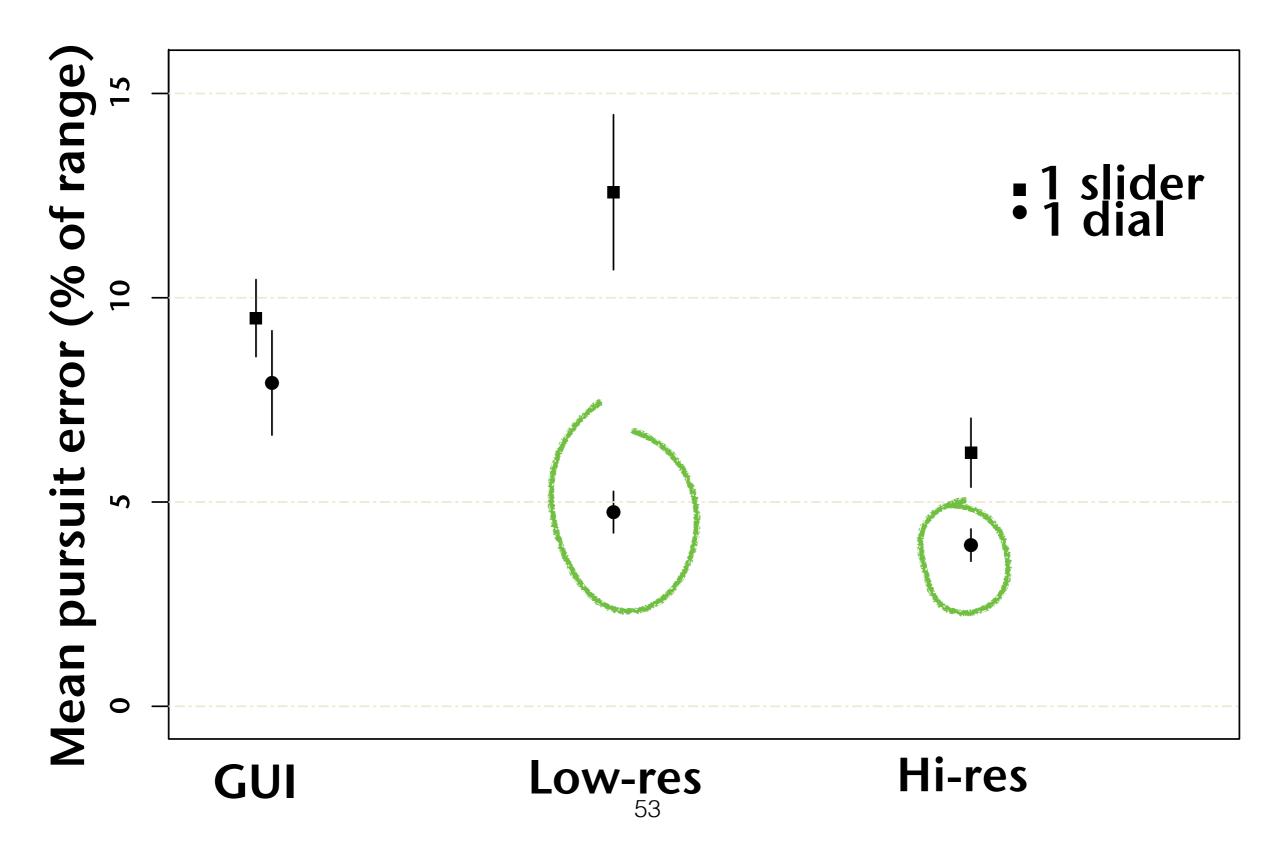
- 18 participants; 50 minute sessions
- Format:
  - Concept design video
  - Training
  - Tasks
  - Structured interview

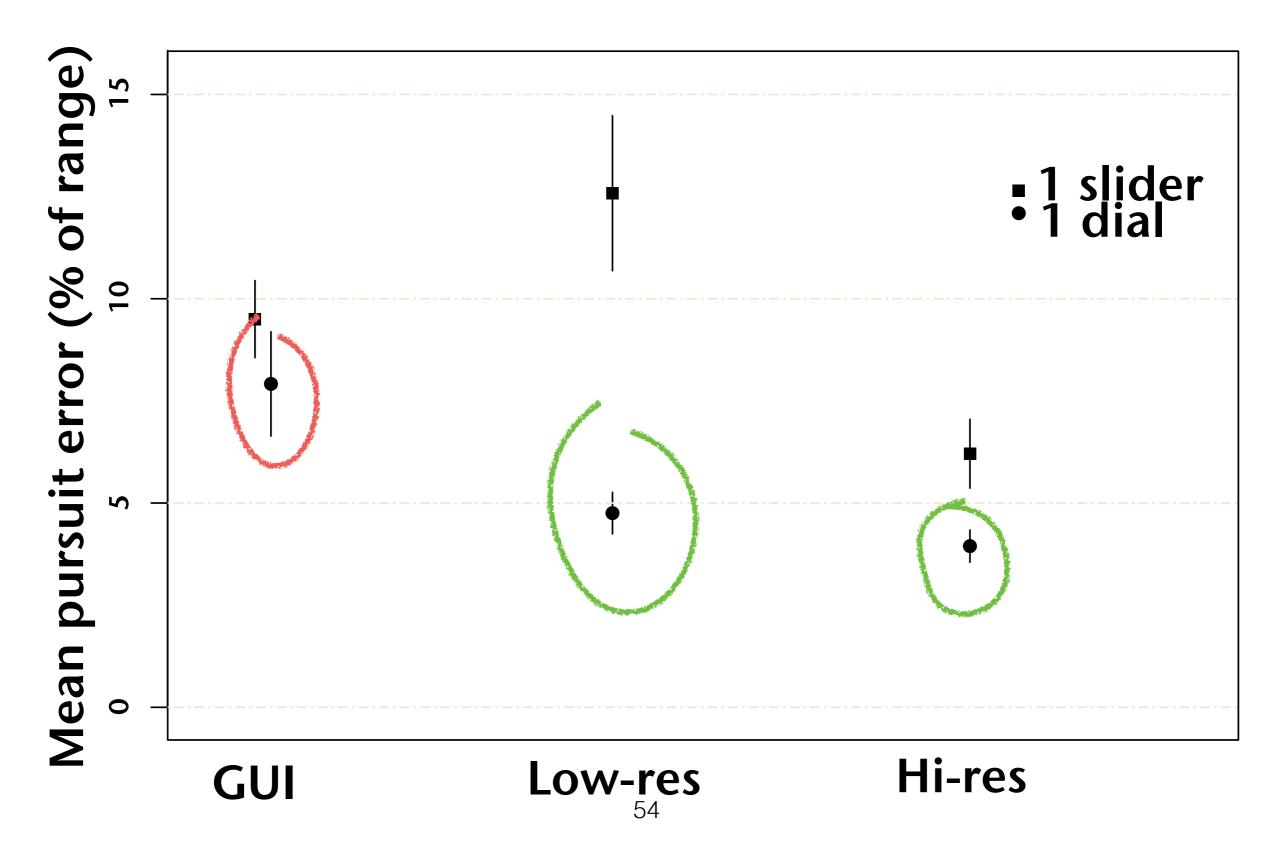
#### Measures

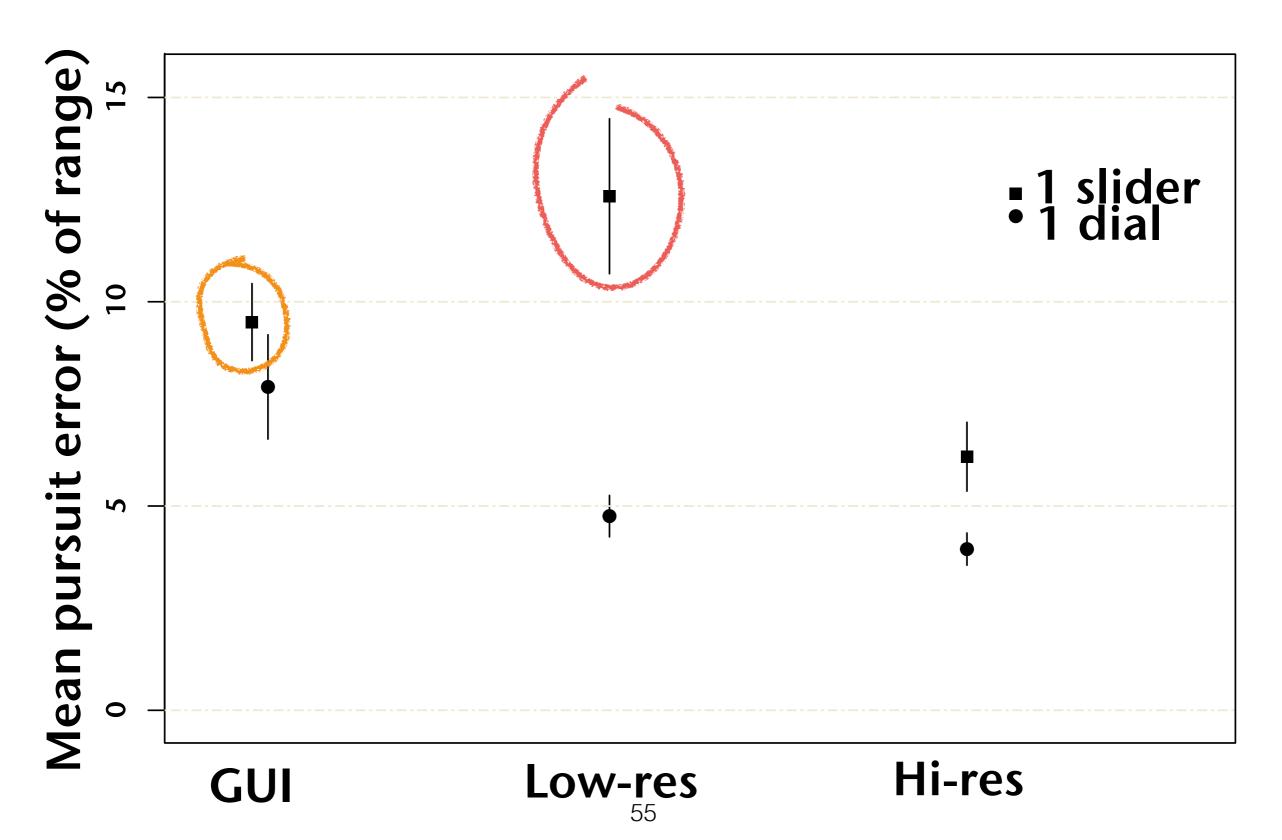
- Pursuit accuracy
- Visual attention required
- Perceived usability
  - Ease of use (1 − 10)
  - Rank interfaces in order of perceived visual attention required

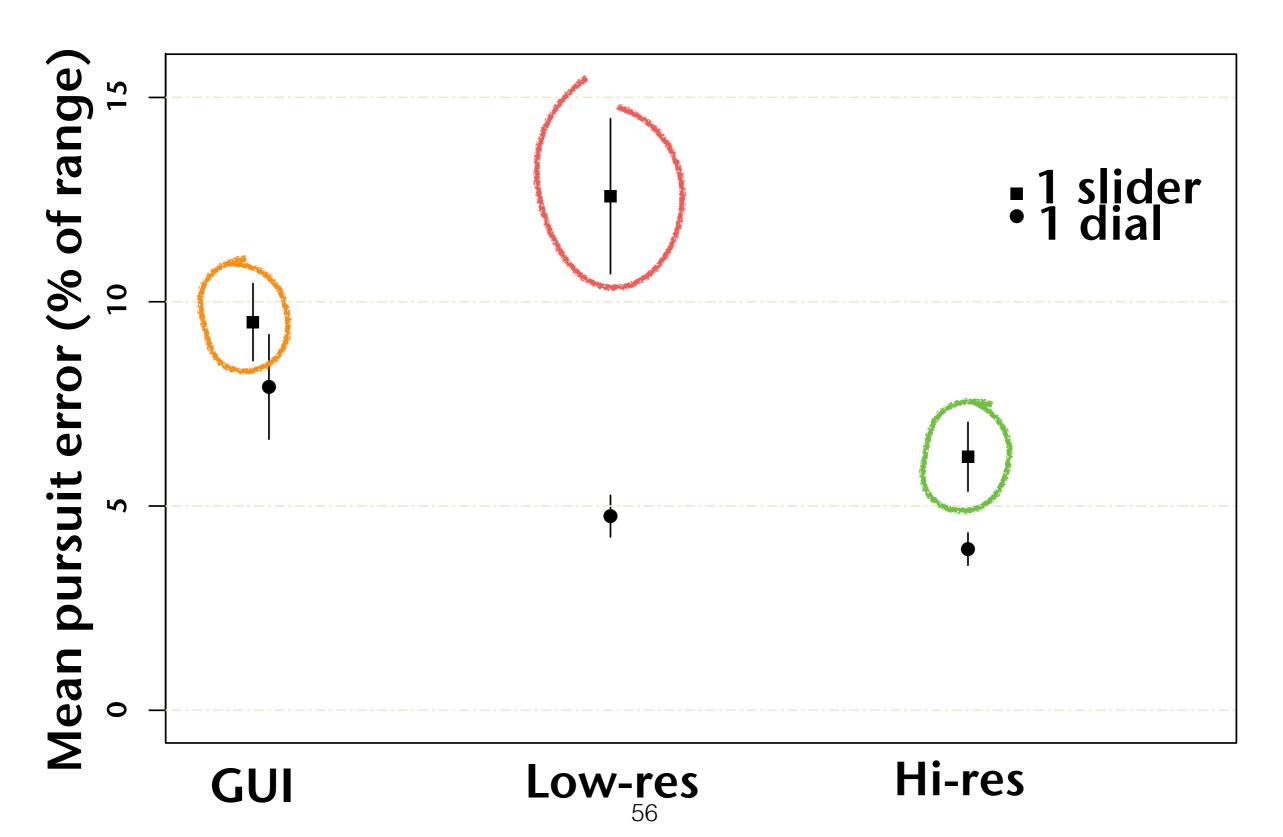
#### Results



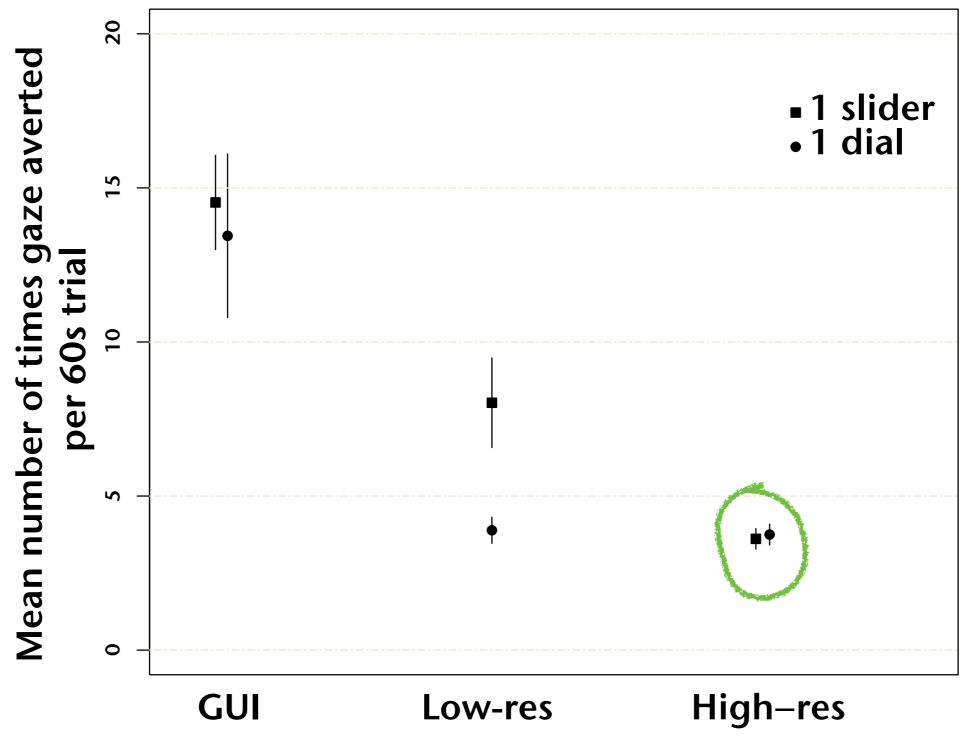




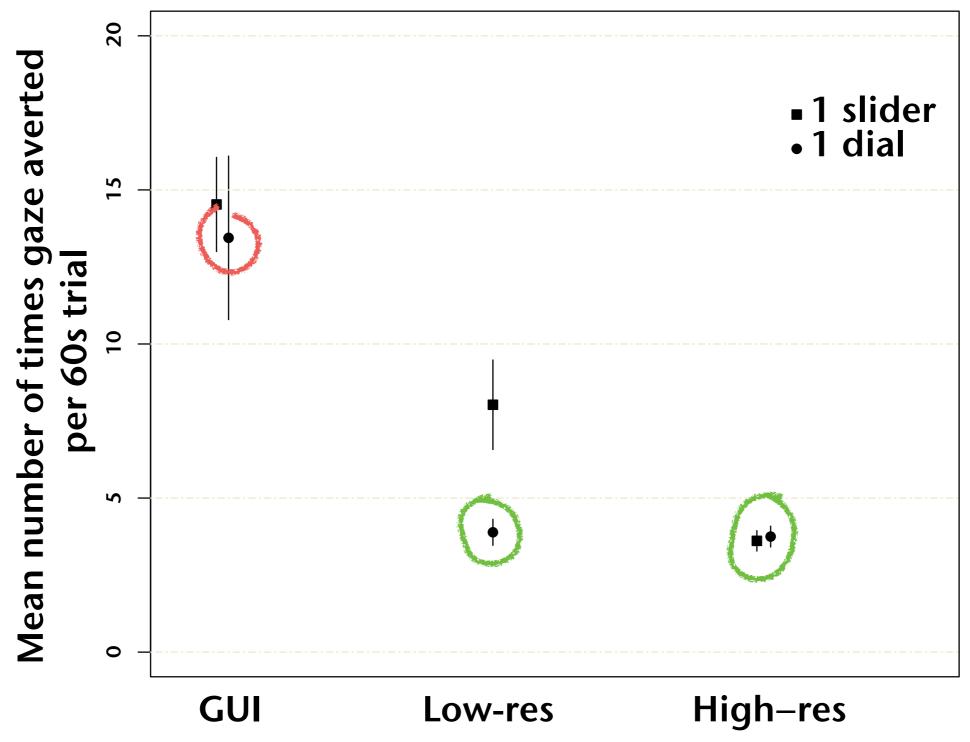




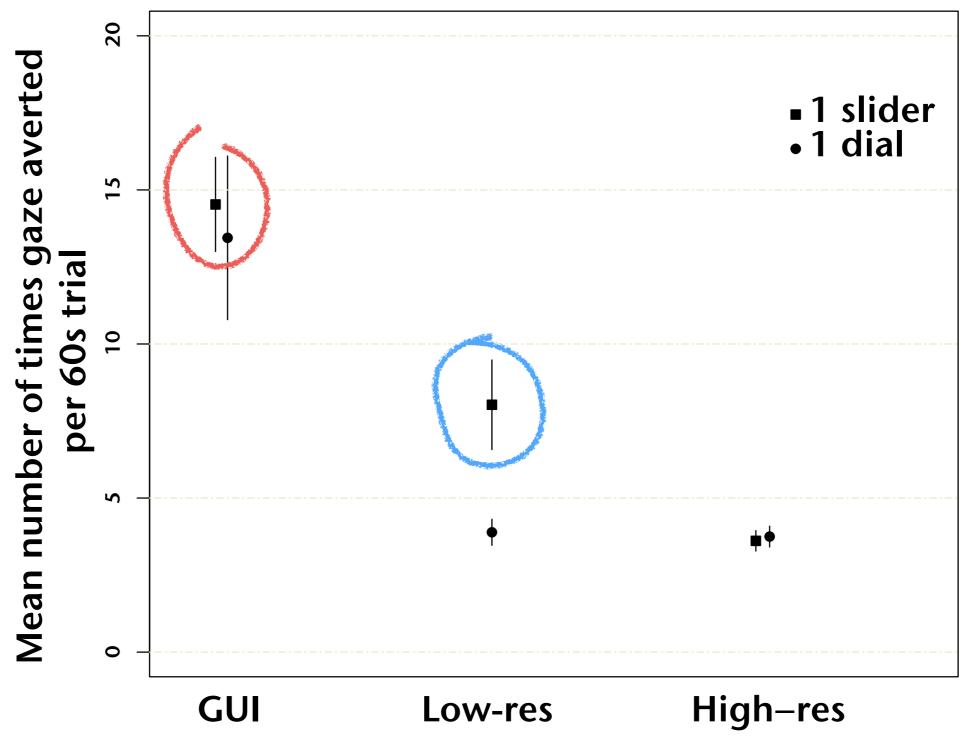
#### Visual Attention



#### Visual Attention



#### Visual Attention



# Users' preferences

- Hi-res most preferred (8.8 / 10)
- Low-res promising (4.8 / 10)
- GUI least preferred (3.4 / 10)

# Summary

- Accuracy
  - Dial
  - Slider
- Visual Attention
- Perceived Usability

# Conclusions

- We have presented emergable surfaces for eyesfree control of continuous widgets
- Future Work:
  - How to do higher resolution emergeable dials?
  - How to improve interaction with emergeable sliders?

# Thank you



# Emergeables: Deformable Displays for Continuous Eyes-Free Mobile Interaction

Simon Robinson

#### Céline Coutrix Jennifer Pearson

Juan Rosso Matheus Fernandes Torquato Laurence Nigay Matt Jones

