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Sweep-Shake: Finding Digital Resources in Physical Environments

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Overview

- Motivation
- Background → Our approach
- Sweep-Shake system
- Exploratory trial → User study
- Results
- Conclusions

Motivation

- Finding geo-tagged information about the places around you
- Engaging with surroundings:
Often need to divide attention
- No reliance on screen for initial discovery
 - Lightweight, casual interaction
 - Filtering of information



Background

- Spatial Information Appliances (Egenhofer [4])
- Point to Discover (Fröhlich *et al.* [5], Simon *et al.* [15])
- Bearing-based selection (Strachan, Murray-Smith [16])
- Vibrotactile waist belt (Van Erp *et al.* [18])
- Earcons (Brewster *et al.* [2])
- AudioGPS (Holland *et al.* [7])

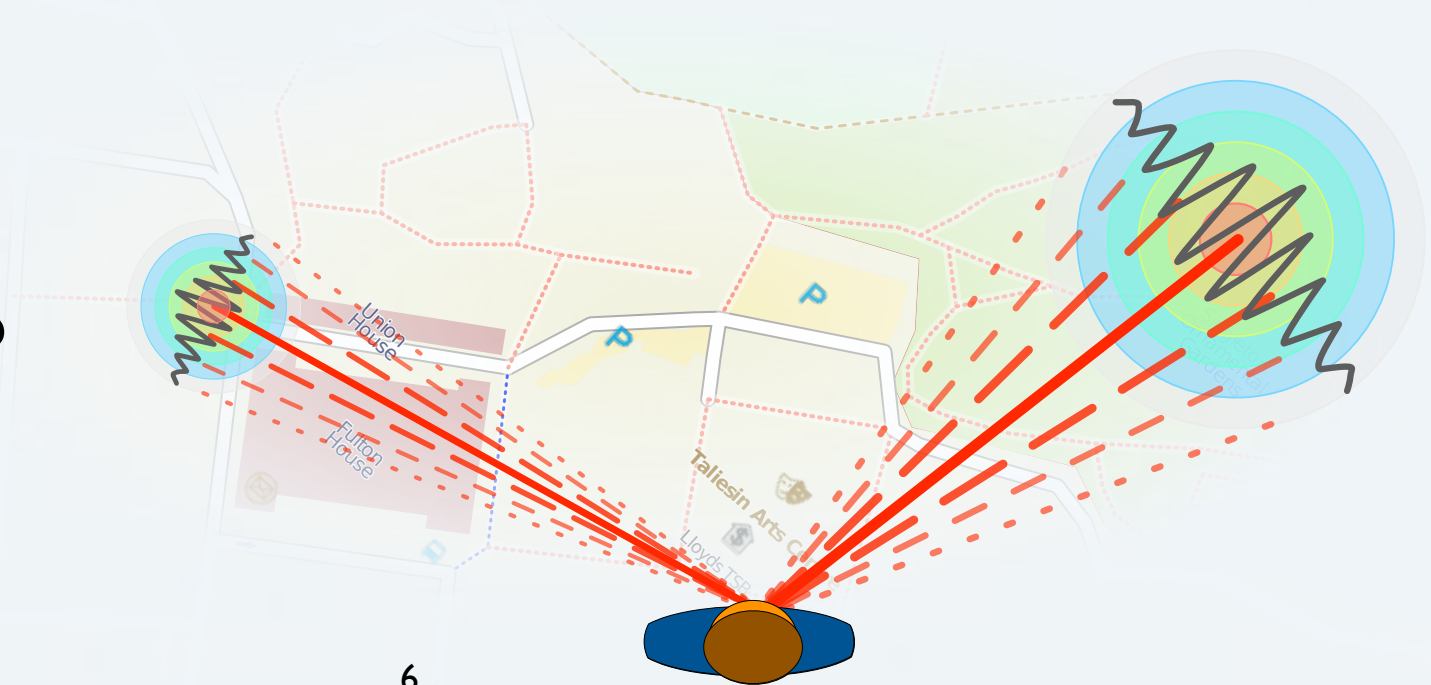
Our approach: Sweep-Shake

- Haptic feedback for direction
- Gestures to refine selection
- Heads-up



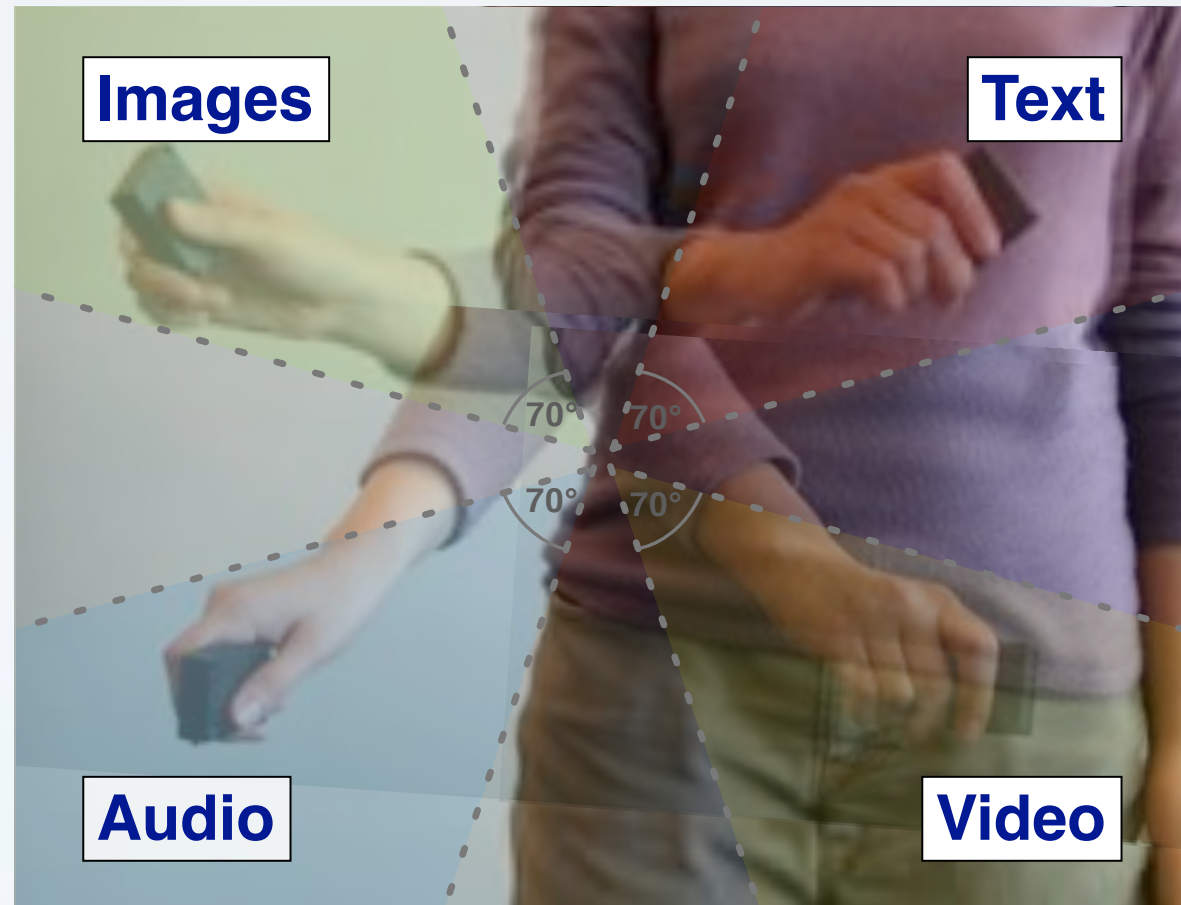
Mode I: Discovering places (browsing)

- Sweep the device to scan the area
- Feedback felt when pointing at a target
 - Direction
 - Size
- Press button to explore further



Mode 2: Filtering information

- Simple gestures
 - 4 categories
 - Small pointing movements to filter
- Once found, press to view (on UMPC)



Proposed benefits

- Seeking of real-world digital resources without looking at a screen
- Encourage interaction with the surroundings rather than the device

Initial exploratory trial

- 4 participants, explore campus at will
 - Verbal feedback
 - Observed behaviours
- Positive feedback
 - Enjoyed interaction method
 - Some used as background cue: Heads-up
 - Less interested in audio/video content
 - Save for later?

User study

- Focus on discovery and selection process: simulated targets
 - Scan device to discover
 - Press button to select
 - Search for filtered information types
 - Find and select each one
 - Repeat
- Compare to visual system...

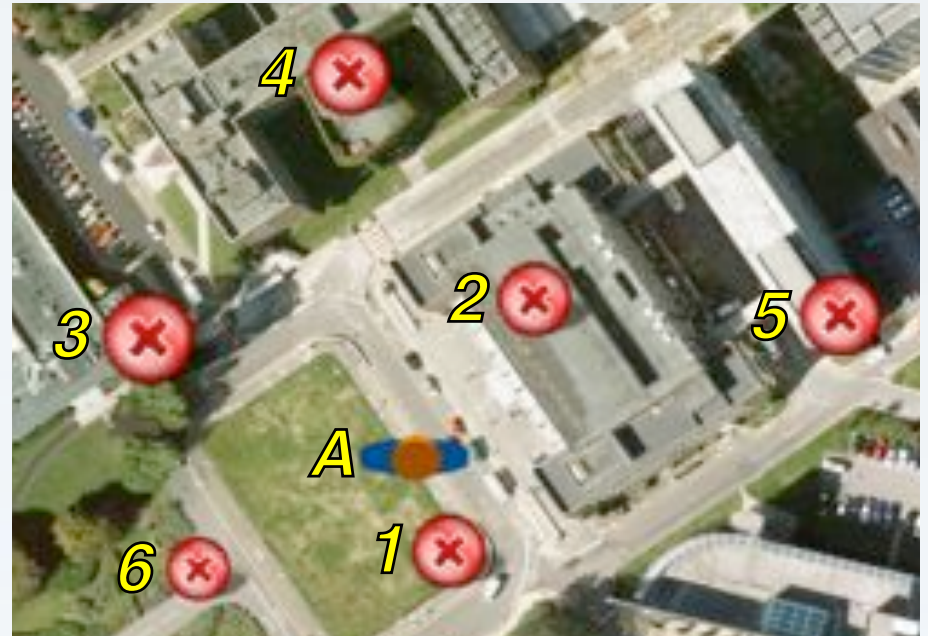
Prototype 2: Visual

- Visual analog of haptic
- Rotating aerial view
- Same method for scanning
- Touch for filtering
- Heads down



User study: Method

- 32 participants
- 6 targets
- Fixed participant location

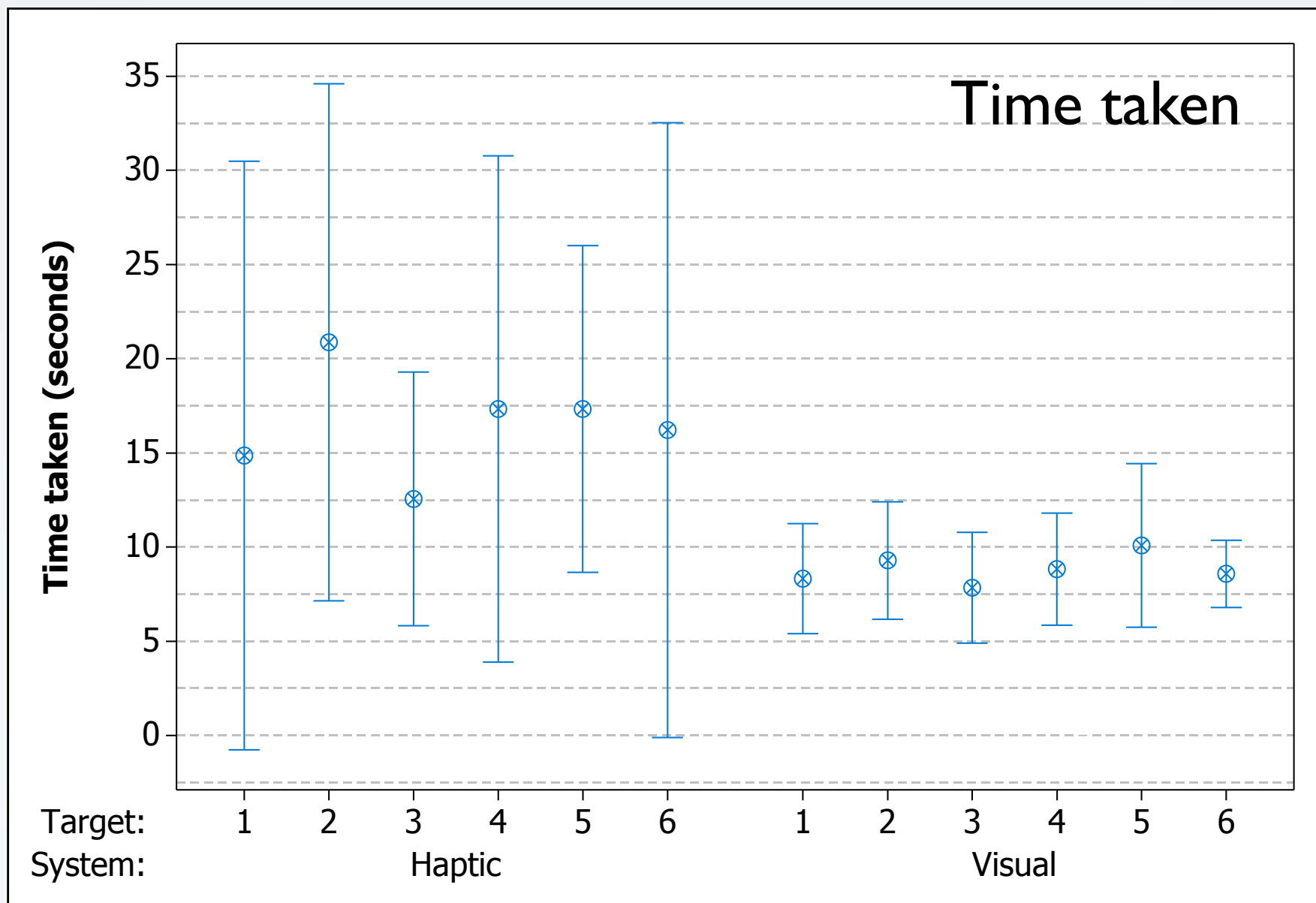


- Between groups, gather:
 - Success rate; time taken; false positives
 - Observed behaviours; verbal feedback

Results: Discovering targets

Measurement	Sweep-Shake	Visual
Targets found (of 6)	75%	97%
Time to select (secs, per target)	16.5 (sd: 22.3)	8.8 (sd: 5.6)
Overall time (secs)	105.2 (sd: 32.3)	81.7 (sd: 26.4)
False positives (per target)	0.9 (sd: 1.1)	0.9 (sd: 0.6)

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Verbal feedback

- Liked haptics
 - *'fun', 'easy'*
- Saw value in heads-up interaction
 - *'More helpful than my GPS'*
 - *'Guide me'* mode requested
- But: can be hard to interpret
 - Feedback and mode clarification needed

Conclusions

- Haptic feedback can offer heads-up interaction
- Users appreciated haptic feedback
- Issues with usability
 - Work needed on modes

Conclusions

- Haptic not yet on-par with visual
 - Lack of familiarity
 - Getting closer...
- Visual has its own issues
 - False positives similar to haptic

Ongoing work

- Haptic feedback in other situations
 - Find objects instead of place information
 - Navigation instead of sat-nav
 - Multi-level hierarchy
- Completely on-phone
 - Low-cost applications - no specific hardware
- Projector for visual content

Thank you

- Questions?
- cssimonr@swan.ac.uk
- <http://cs.swan.ac.uk/negotiatedinteraction>
- Research funded by EPSRC project EP/E042171/1, undertaken in collaboration with colleagues at Glasgow University



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